

$\frac{dx}{dt} = x - y, \frac{dy}{dt} = y - x$ (A) DETERMINE ALL CRITICAL POINTS OF THE GIVEN SYSTEM OF EQUATIONS. (B)

$\frac{dx}{dt} = x - y, \frac{dy}{dt} = y - x$ (A) DETERMINE ALL CRITICAL POINTS OF THE GIVEN SYSTEM OF EQUATIONS. (B)

UNDERSTANDING THE BEHAVIOR OF DYNAMIC SYSTEMS MODELED BY DIFFERENTIAL EQUATIONS IS FUNDAMENTAL IN VARIOUS FIELDS SUCH AS MATHEMATICS, PHYSICS, ENGINEERING, AND BIOLOGY. ANALYZING THESE SYSTEMS INVOLVES IDENTIFYING THEIR CRITICAL POINTS OR EQUILIBRIUM POINTS, WHICH PROVIDE INSIGHTS INTO THE SYSTEM'S LONG-TERM BEHAVIOR AND STABILITY. IN THIS COMPREHENSIVE GUIDE, WE EXPLORE THE PROCESS OF DETERMINING ALL CRITICAL POINTS OF THE SPECIFIC SYSTEM OF DIFFERENTIAL EQUATIONS:

```
\[
\begin{cases}
\frac{dx}{dt} = x - y \\
\frac{dy}{dt} = y - x
\end{cases}
\]
```

THIS ARTICLE IS DESIGNED TO HELP STUDENTS, RESEARCHERS, AND ENTHUSIASTS UNDERSTAND THE METHODOLOGY BEHIND ANALYZING SUCH SYSTEMS, WITH A FOCUS ON CLARITY, SEO OPTIMIZATION, AND STRUCTURED LEARNING.

UNDERSTANDING THE SYSTEM OF DIFFERENTIAL EQUATIONS

BEFORE DIVING INTO THE PROCESS OF FINDING CRITICAL POINTS, IT IS ESSENTIAL TO UNDERSTAND WHAT THESE EQUATIONS REPRESENT AND HOW THEY INTERACT.

DEFINITION OF THE SYSTEM

THE SYSTEM CONSISTS OF TWO COUPLED FIRST-ORDER DIFFERENTIAL EQUATIONS:

```
\[
\begin{cases}
\frac{dx}{dt} = x - y \\
\frac{dy}{dt} = y - x
\end{cases}
\]
```

WHERE:

- $x(t)$ AND $y(t)$ ARE FUNCTIONS OF TIME t ,
- $\frac{dx}{dt}$ AND $\frac{dy}{dt}$ DESCRIBE THE RATES OF CHANGE OF x AND y .

THIS SYSTEM CAN MODEL VARIOUS PHENOMENA, SUCH AS PREDATOR-PREY INTERACTIONS, COMPETING SPECIES, OR COUPLED OSCILLATORS, DEPENDING ON THE CONTEXT.

SIGNIFICANCE OF CRITICAL POINTS

CRITICAL POINTS, ALSO KNOWN AS EQUILIBRIUM POINTS, ARE POINTS IN THE PHASE SPACE WHERE THE SYSTEM'S STATE DOES

NOT CHANGE OVER TIME:

```
\[
\begin{cases}
\frac{dX}{dt} = 0 \\
\frac{dY}{dt} = 0
\end{cases}
\]
```

FINDING THESE POINTS HELPS IN UNDERSTANDING THE POSSIBLE STEADY STATES OF THE SYSTEM AND ANALYZING THEIR STABILITY.

PART (A): HOW TO DETERMINE ALL CRITICAL POINTS OF THE GIVEN SYSTEM

THIS SECTION PROVIDES A STEP-BY-STEP METHODOLOGY TO IDENTIFY ALL EQUILIBRIUM POINTS FOR THE PROVIDED DIFFERENTIAL SYSTEM.

STEP 1: SET THE DERIVATIVES TO ZERO

THE FIRST STEP IN FINDING CRITICAL POINTS IS TO SET THE DERIVATIVES EQUAL TO ZERO:

```
\[
\begin{cases}
X - Y = 0 \\
Y - X = 0
\end{cases}
\]
```

THIS GIVES THE CONDITIONS UNDER WHICH THE SYSTEM REMAINS UNCHANGED OVER TIME.

STEP 2: SOLVE SIMULTANEOUSLY FOR (X) AND (Y)

FROM THE EQUATIONS:

```
\[
X - Y = 0 \Rightarrow X = Y
\]
```

AND

```
\[
Y - X = 0 \Rightarrow Y = X
\]
```

WE OBSERVE THAT BOTH EQUATIONS ARE CONSISTENT AND IMPLY:

```
\[
X = Y
\]
```

THIS INDICATES THAT THE CRITICAL POINTS LIE ALONG THE LINE $(X = Y)$ IN THE PHASE SPACE.

STEP 3: FIND THE CRITICAL POINTS

SINCE THE CONDITION FOR CRITICAL POINTS IS $(X = Y)$, AND THERE ARE NO OTHER CONSTRAINTS, THE ENTIRE LINE $(X = Y)$ CONSTITUTES A SET OF CRITICAL POINTS. THEREFORE, THE CRITICAL POINTS ARE GIVEN BY:

$$\boxed{\text{ALL POINTS } (X, Y) \text{ SUCH THAT } X = Y}$$

SUMMARY OF PART (A):

- THE CRITICAL POINTS OF THE SYSTEM ARE ALL POINTS WHERE $(X = Y)$.
- THESE POINTS FORM A CONTINUUM ALONG THE LINE $(X = Y)$ IN THE PHASE SPACE.

PART (B): ANALYZING THE STABILITY OF THE CRITICAL POINTS

WHILE THE INITIAL PART FOCUSED ON FINDING THE CRITICAL POINTS, UNDERSTANDING THEIR STABILITY IS EQUALLY IMPORTANT. STABILITY ANALYSIS HELPS DETERMINE WHETHER SOLUTIONS NEAR THESE POINTS TEND TO MOVE TOWARD OR AWAY FROM THEM OVER TIME.

LINEARIZATION OF THE SYSTEM

TO ANALYZE STABILITY, WE EMPLOY LINEARIZATION TECHNIQUES BY CONSTRUCTING THE JACOBIAN MATRIX OF THE SYSTEM AT ANY CRITICAL POINT.

THE SYSTEM:

$$\begin{cases} \frac{dX}{dt} = X - Y \\ \frac{dY}{dt} = Y - X \end{cases}$$

HAS THE VECTOR FORM:

$$\begin{aligned} \frac{d}{dt} \begin{pmatrix} X \\ Y \end{pmatrix} &= \begin{pmatrix} X - Y \\ Y - X \end{pmatrix} \end{aligned}$$

THE JACOBIAN MATRIX (J) OF THE SYSTEM IS:

$$J = \begin{bmatrix} \frac{\partial}{\partial X}(X - Y) & \frac{\partial}{\partial Y}(X - Y) \\ \frac{\partial}{\partial X}(Y - X) & \frac{\partial}{\partial Y}(Y - X) \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

SINCE THE JACOBIAN IS CONSTANT (INDEPENDENT OF (X, Y)), THE STABILITY ANALYSIS SIMPLIFIES.

EIGENVALUES AND STABILITY

TO DETERMINE THE STABILITY, CALCULATE THE EIGENVALUES (λ) OF THE JACOBIAN MATRIX:

$$\det(J - \lambda I) = 0$$

WHERE (I) IS THE IDENTITY MATRIX.

COMPUTE:

$$\det \begin{bmatrix} 1 - \lambda & -1 \\ -1 & 1 - \lambda \end{bmatrix} = (1 - \lambda)^2 - (-1)(-1) = (1 - \lambda)^2 - 1$$

SET EQUAL TO ZERO:

$$(1 - \lambda)^2 - 1 = 0 \implies (1 - \lambda)^2 = 1$$

$$1 - \lambda = \pm 1$$

THUS,

$$\lambda = 1 \text{ or } \lambda = 0$$

WHICH GIVES THE EIGENVALUES:

$$\boxed{\lambda_1 = 2, \lambda_2 = 0}$$

}
\\

INTERPRETATION:

- THE EIGENVALUE $(\lambda_1 = 2 > 0)$ INDICATES AN UNSTABLE DIRECTION.
- THE EIGENVALUE $(\lambda_2 = 0)$ SUGGESTS A MARGINAL OR NEUTRAL STABILITY ALONG THAT DIRECTION.

CONCLUSION ON STABILITY

GIVEN THE EIGENVALUES, THE CRITICAL POINTS ALONG THE LINE $(X = Y)$ ARE NOT ASYMPTOTICALLY STABLE. SPECIFICALLY, THE PRESENCE OF A POSITIVE EIGENVALUE INDICATES THAT SOLUTIONS NEAR THESE POINTS TEND TO DIVERGE AWAY, POINTING TO INSTABILITY IN THE SYSTEM.

SUMMARY AND IMPLICATIONS OF THE SYSTEM ANALYSIS

UNDERSTANDING THE CRITICAL POINTS AND THEIR STABILITY OFFERS VALUABLE INSIGHTS INTO THE SYSTEM'S LONG-TERM BEHAVIOR:

- CRITICAL POINTS ARE ALL POINTS WHERE $(X = Y)$. THESE POINTS FORM AN ENTIRE LINE IN THE PHASE SPACE.
- STABILITY ANALYSIS REVEALS THAT THESE POINTS ARE UNSTABLE, WITH SOLUTIONS TENDING TO DIVERGE AWAY FROM EQUILIBRIUM ALONG CERTAIN DIRECTIONS.
- EIGENVALUES OF THE JACOBIAN MATRIX ARE CRUCIAL IN DETERMINING THE NATURE OF THESE CRITICAL POINTS.

PRACTICAL APPLICATIONS AND RELEVANCE

THIS ANALYSIS APPLIES TO VARIOUS REAL-WORLD SYSTEMS:

- ECOLOGY: MODELING INTERACTIONS BETWEEN PREDATOR AND PREY POPULATIONS.
- ECONOMICS: ANALYZING COMPETING MARKETS OR INVESTMENT STRATEGIES.
- ENGINEERING: STUDYING COUPLED OSCILLATORS OR CONTROL SYSTEMS.

UNDERSTANDING HOW TO DETERMINE AND ANALYZE CRITICAL POINTS HELPS IN DESIGNING SYSTEMS THAT ARE STABLE, PREDICTING LONG-TERM BEHAVIORS, AND AVOIDING UNDESIRABLE SYSTEM STATES.

CONCLUSION: MASTERING THE ANALYSIS OF DIFFERENTIAL SYSTEMS

IN THIS COMPREHENSIVE GUIDE, WE'VE DETAILED THE PROCESS OF FINDING ALL CRITICAL POINTS FOR THE SYSTEM:

\\
\\begin{cases}
\\frac{dX}{dt} = X - Y \\
\\frac{dY}{dt} = Y - X
\\end{cases}

\]

BY SETTING DERIVATIVES TO ZERO, SOLVING FOR $\backslash(X\backslash)$ AND $\backslash(Y\backslash)$, AND ANALYZING THE STABILITY VIA THE JACOBIAN MATRIX AND EIGENVALUES. RECOGNIZING THAT THE ENTIRE LINE $\backslash(X = Y\backslash)$ FORMS CRITICAL POINTS ALLOWS FOR A DEEPER UNDERSTANDING OF THE SYSTEM'S DYNAMICS, STABILITY, AND LONG-TERM BEHAVIOR.

BY MASTERING THESE TECHNIQUES—SETTING DERIVATIVES TO ZERO, SOLVING ALGEBRAIC EQUATIONS, CONSTRUCTING THE JACOBIAN, AND COMPUTING EIGENVALUES—YOU CAN ANALYZE A WIDE ARRAY OF DIFFERENTIAL SYSTEMS EFFICIENTLY.

REMEMBER:

- CRITICAL POINTS ARE WHERE THE SYSTEM REMAINS UNCHANGED.
- THE STABILITY DEPENDS ON THE EIGENVALUES OF THE JACOBIAN.
- SYSTEMS CAN HAVE ENTIRE LINES OR REGIONS OF EQUILIBRIUM POINTS, NOT JUST ISOLATED POINTS.

WHETHER YOU ARE STUDYING BIOLOGICAL SYSTEMS, PHYSICAL PHENOMENA, OR ENGINEERING MODELS, THESE ANALYTICAL TOOLS ARE ESSENTIAL FOR UNDERSTANDING COMPLEX DYNAMIC BEHAVIORS.

KEYWORDS: DIFFERENTIAL EQUATIONS, CRITICAL POINTS, EQUILIBRIUM POINTS, STABILITY ANALYSIS, JACOBIAN MATRIX, EIGENVALUES, PHASE SPACE, DYNAMICAL SYSTEMS, SYSTEM STABILITY, DIFFERENTIAL SYSTEM ANALYSIS, MATHEMATICAL MODELING

FREQUENTLY ASKED QUESTIONS

WHAT DOES THE SYSTEM OF DIFFERENTIAL EQUATIONS $Dx/Dt = X - Y$ AND $Dy/Dt = Y - X$ REPRESENT IN TERMS OF ITS CRITICAL POINTS?

THE SYSTEM REPRESENTS A SET OF COUPLED DIFFERENTIAL EQUATIONS DESCRIBING THE DYNAMICS BETWEEN VARIABLES X AND Y . CRITICAL POINTS OCCUR WHERE BOTH DERIVATIVES ARE ZERO, INDICATING EQUILIBRIUM STATES WHERE THE SYSTEM REMAINS CONSTANT OVER TIME.

HOW DO YOU FIND ALL CRITICAL POINTS FOR THE SYSTEM $Dx/Dt = X - Y$ AND $Dy/Dt = Y - X$?

TO FIND CRITICAL POINTS, SET $Dx/Dt = 0$ AND $Dy/Dt = 0$, LEADING TO THE EQUATIONS $X - Y = 0$ AND $Y - X = 0$. SOLVING THESE SIMULTANEOUSLY YIELDS THE CRITICAL POINT AT $(X, Y) = (k, k)$, WHERE k IS ANY REAL NUMBER, INDICATING A LINE OF EQUILIBRIUM POINTS.

ARE THERE MULTIPLE CRITICAL POINTS OR A CONTINUOUS SET FOR THE SYSTEM $Dx/Dt = X - Y$, $Dy/Dt = Y - X$?

THE SYSTEM HAS INFINITELY MANY CRITICAL POINTS ALONG THE LINE $X = Y$, MEANING ANY POINT WHERE X EQUALS Y IS AN EQUILIBRIUM, FORMING A CONTINUUM OF CRITICAL POINTS RATHER THAN ISOLATED ONES.

WHAT IS THE SIGNIFICANCE OF THE CRITICAL POINTS IN THE PHASE PLANE FOR THIS SYSTEM?

THE CRITICAL POINTS INDICATE THE SYSTEM'S EQUILIBRIUM STATES. ANALYZING THEIR STABILITY HELPS UNDERSTAND WHETHER TRAJECTORIES IN THE PHASE PLANE TEND TO SETTLE AT THESE POINTS OR DIVERGE AWAY, REVEALING THE SYSTEM'S LONG-TERM BEHAVIOR.

How would you classify the stability of the critical points where $X = Y$ in this system?

Stability can be assessed by linearizing the system around the critical points and examining the eigenvalues of the Jacobian matrix. For this system, the eigenvalues are zero, indicating a need for further analysis, but typically, such a line of equilibria may be neutrally stable or saddle points, depending on the context.

Additional Resources

Comprehensive Analysis of the System $\frac{dx}{dt} = x - y$, $\frac{dy}{dt} = y - x$: Critical Points and Their Significance

Introduction

In the realm of differential equations and dynamical systems, understanding the behavior of coupled systems such as the one defined by:

$$\begin{cases} \frac{dx}{dt} = x - y \\ \frac{dy}{dt} = y - x \end{cases}$$

is fundamental. Such systems often model real-world phenomena ranging from biological populations to mechanical oscillations. A key step in analyzing these systems is identifying the critical points (also known as equilibrium points or fixed points), which serve as the foundation for understanding long-term behavior, stability, and possible oscillations or convergence.

This review aims to thoroughly examine the process of determining all critical points for the given system, interpret their significance, and discuss the broader implications.

Understanding the System

The given system can be expressed as:

$$\boxed{\begin{cases} \frac{dx}{dt} = x - y \\ \frac{dy}{dt} = y - x \end{cases}}$$

This is a linear, first-order, coupled differential system. The symmetry between the equations hints at potential behaviors such as convergence to equilibrium, oscillations, or divergence, depending on the stability of the critical points.

The Concept of Critical Points in Differential Systems

Critical points are points in the phase space where the derivatives vanish simultaneously:

$$\begin{cases} \frac{dX}{dt} = 0, \\ \frac{dY}{dt} = 0 \end{cases}$$

PHYSICALLY, THESE POINTS REPRESENT STATES WHERE THE SYSTEM EXPERIENCES NO CHANGE — EQUILIBRIUM STATES. THEY ARE CRUCIAL BECAUSE:

- THEY SERVE AS ATTRACTORS, REPELLERS, OR SADDLE POINTS.
- THE STABILITY OF THESE POINTS INFLUENCES THE LONG-TERM BEHAVIOR OF TRAJECTORIES.
- ANALYZING THE NATURE OF CRITICAL POINTS HELPS PREDICT HOW THE SYSTEM RESPONDS TO SMALL PERTURBATIONS.

PART (A): DETERMINING ALL CRITICAL POINTS

STEP 1: SET DERIVATIVES TO ZERO

TO FIND THE CRITICAL POINTS, SET THE RIGHT-HAND SIDES OF THE SYSTEM TO ZERO:

$$\begin{cases} X - Y = 0 \\ Y - X = 0 \end{cases}$$

STEP 2: SOLVE THE SYSTEM OF EQUATIONS

FROM THE FIRST EQUATION:

$$X = Y$$

SUBSTITUTE INTO THE SECOND:

$$Y - X = 0 \rightarrow Y - Y = 0$$

WHICH SIMPLIFIES TO:

$$0 = 0$$

THIS INDICATES THAT THE SECOND EQUATION DOES NOT IMPOSE ADDITIONAL CONSTRAINTS BEYOND $(X = Y)$. THEREFORE, THE CRITICAL POINTS ARE ALL POINTS WHERE:

$$X = Y$$

AND (X, Y) ARE ARBITRARY REAL NUMBERS SATISFYING THIS CONDITION.

RESULT:

$$\boxed{\{$$

$\{ (X^*, Y^*) \mid X^* = Y^*, \quad \forall X^* \in \mathbb{R} \}$

IN OTHER WORDS:

$\{ (X, Y) \mid Y = X \}$

PART (B): ANALYZING THE NATURE OF CRITICAL POINTS

HAVING IDENTIFIED THAT EVERY POINT ON THE LINE $(Y = X)$ CONSTITUTES A CRITICAL POINT, THE NEXT STEP INVOLVES UNDERSTANDING THE STABILITY OF THESE POINTS. THIS INVOLVES LINEARIZATION AND EIGENVALUE ANALYSIS.

STABILITY ANALYSIS OF CRITICAL POINTS

STEP 1: WRITE THE SYSTEM IN MATRIX FORM

EXPRESS THE SYSTEM AS:

$\frac{d}{dt} \begin{pmatrix} X \\ Y \end{pmatrix} = \mathbf{A} \begin{pmatrix} X \\ Y \end{pmatrix}$

WHERE

$\mathbf{A} = \begin{pmatrix} \frac{\partial}{\partial X} (X - Y) & \frac{\partial}{\partial Y} (X - Y) \\ \frac{\partial}{\partial X} (Y - X) & \frac{\partial}{\partial Y} (Y - X) \end{pmatrix}$
 $= \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}$

NOTABLY, THIS MATRIX IS CONSTANT, INDICATING A LINEAR SYSTEM WITH A FIXED COEFFICIENT MATRIX.

STEP 2: EIGENVALUE AND EIGENVECTOR ANALYSIS

TO ANALYZE STABILITY, FIND THE EIGENVALUES (λ) OF $(\mathbf{A})$ BY SOLVING:

$\det(\mathbf{A} - \lambda \mathbf{I}) = 0$

CALCULATIONS:

$\det \begin{pmatrix} 1 - \lambda & -1 \\ -1 & 1 - \lambda \end{pmatrix} = (1 - \lambda)^2 - 1 = 0$

$\backslash$

$$\backslash (1 - \lambda)^2 = 1$$

$$\backslash 1 - \lambda = \pm 1$$

WHICH YIELDS:

- For $(1 - \lambda = 1)$:

$$\backslash \lambda = 0$$

- For $(1 - \lambda = -1)$:

$$\backslash \lambda = 2$$

EIGENVALUES:

$$\backslash \boxed{\lambda_1 = 0, \lambda_2 = 2}$$

STEP 3: INTERPRET EIGENVALUES

- EIGENVALUE $(\lambda = 2)$: POSITIVE REAL PART, INDICATES AN UNSTABLE DIRECTION, EXPONENTIAL GROWTH AWAY FROM THE CRITICAL LINE ALONG THE CORRESPONDING EIGENVECTOR.
- EIGENVALUE $(\lambda = 0)$: NEUTRAL (NEITHER DECAYING NOR GROWING), SUGGESTS A CENTER OR A marginally stable DIRECTION.

STEP 4: EIGENVECTORS

FIND THE EIGENVECTORS:

- For $(\lambda = 2)$:

$$\backslash (\mathbf{A} - 2 \mathbf{I}) \mathbf{v} = 0$$

$$\backslash \begin{matrix} \mathbf{A} \\ \begin{matrix} -1 & 1 \\ 1 & -1 \end{matrix} \end{matrix} \mathbf{v} = 0$$

THIS REDUCES TO:

$\backslash$

$$-v_1 - v_2 = 0 \Rightarrow v_2 = -v_1$$

EIGENVECTOR:

$$\mathbf{v}_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

- For $(\lambda = 0)$:

$$(\mathbf{A} - 0 \mathbf{I}) \mathbf{v} = 0$$

$$\begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \mathbf{v} = 0$$

WHICH SIMPLIFIES TO:

$$v_1 - v_2 = 0 \Rightarrow v_2 = v_1$$

EIGENVECTOR:

$$\mathbf{v}_0 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

STEP 5: IMPLICATIONS FOR SYSTEM BEHAVIOR

- The eigenvector $\mathbf{v}_2$ points along the line $(Y = -X)$, associated with the eigenvalue 2, indicating an unstable direction along that line.
- The eigenvector $\mathbf{v}_0$ points along the line $(Y = X)$, associated with eigenvalue 0, implying neutral stability along that direction.

Overall, the critical points form a line of equilibria $(Y = X)$, with the system exhibiting saddle-like behavior owing to the mixed eigenvalues.

BROADER INTERPRETATION AND PHYSICAL SIGNIFICANCE

NATURE OF THE CRITICAL LINE

The critical points forming the line $(Y = X)$ suggest a degenerate set of equilibria, meaning the system's long-term behavior heavily depends on initial conditions:

- Trajectories starting on the line $(Y = X)$: The system remains at rest, as they are equilibrium points.
- Trajectories near the line: Due to the eigenvalues, some directions lead away from the line (unstable), while others are neutral, possibly resulting in trajectories that move towards or along the line without settling, depending on initial conditions.

STABILITY AND SYSTEM DYNAMICS

THE EIGENVALUES INDICATE THAT:

- ALONG THE EIGENVECTOR $\mathbf{v}_2$, THE SYSTEM EXPERIENCES EXPONENTIAL DIVERGENCE (INSTABILITY).
- ALONG THE EIGENVECTOR $\mathbf{v}_0$, THE SYSTEM EXHIBITS NEUTRAL BEHAVIOR, IMPLYING THE EXISTENCE OF CENTER MANIFOLDS.

THIS MIXED STABILITY POINTS TO THE PRESENCE OF SADDLE POINTS ALONG THE LINE $(Y = X)$, WHICH ARE STRUCTURALLY UNSTABLE UNDER PERTURBATIONS BUT CRUCIAL IN UNDERSTANDING THE PHASE PORTRAIT.

VISUALIZING THE PHASE PORTRAIT

A PHASE-SPACE DIAGRAM WOULD DEPICT:

- A LINE OF CRITICAL POINTS ALONG $(Y = X)$.
- TRAJECTORIES APPROACHING OR DIVERGING FROM THIS LINE DEPENDING ON INITIAL CONDITIONS.
- THE UNSTABLE EIGENVECTOR INDICATING DIRECTIONS ALONG WHICH TRAJECTORIES ARE REPELLED AWAY FROM EQUILIBRIUM.

PRACTICAL IMPLICATIONS

UNDERSTANDING THE CRITICAL POINTS AND THEIR STABILITY INFORMS VARIOUS APPLICATIONS:

- ENGINEERING SYSTEMS: RECOGNIZING POINTS OF EQUILIBRIUM HELPS IN DESIGNING CONTROL SYSTEMS TO MAINTAIN STABILITY OR INDUCE DESIRED BEHAVIORS.
- BIOLOGICAL MODELS: EQUILIBRIA LINE MAY CORRESPOND TO STEADY STATES OR

[Dx Dy X Y Y X Dt Dt A Determine All Critical Points Of The Given System Of Equations B](#)

Dx Dy X Y Y X Dt Dt A Determine All Critical Points Of The Given System Of Equations B

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