

Find The Inverse Laplace Transform $F(t) = \mathcal{L}^{-1}\{F(s)\}$ Of The Function $F(s) = \frac{4s^2 + 81}{(s^2 + 9)^2}$

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Understanding how to find the inverse Laplace transform is a fundamental aspect of solving differential equations, analyzing systems, and processing signals in engineering and mathematics. This article provides a comprehensive guide on how to determine the inverse Laplace transform of a given function, specifically focusing on the function $F(s) = \frac{4s^2 + 81}{(s^2 + 9)^2}$. By exploring the principles, methodologies, and step-by-step procedures, you will gain clarity on how to approach such problems effectively.

Introduction to the Laplace Transform and Its Inverse

The Laplace transform is a powerful integral transform used to convert differential equations from the time domain into the complex frequency domain. This transformation simplifies the process of solving linear differential equations by turning differentiation into algebraic operations.

Definition of the Laplace Transform:

$$\mathcal{L}\{f(t)\} = F(s) = \int_0^{\infty} e^{-st} f(t) dt$$

where:

- $f(t)$ is a time-domain function,
- $F(s)$ is the complex frequency domain representation,
- s is a complex variable $(s = \sigma + i\omega)$.

Inverse Laplace Transform:

The inverse process retrieves $f(t)$ from $F(s)$, often denoted as:

$$f(t) = \mathcal{L}^{-1}\{F(s)\}$$

Finding this inverse is crucial for interpreting solutions back in the time

domain, especially after transforming and manipulating the original differential equations.

Understanding the Function $(F(s) = 4s^2 + 81)$

Before delving into the inverse transformation, it's essential to analyze the structure of $(F(s))$.

- The function $(F(s) = 4s^2 + 81)$ is a polynomial in (s) , indicating that its inverse transform corresponds to derivatives or polynomial functions in (t) .
- Recognizing standard forms and applying properties like linearity, shifting, and differentiation will streamline the process.

Key observations:

- The term $(4s^2)$ suggests a second derivative in the time domain.
- The constant (81) is related to sine or cosine functions when considering inverse transforms involving complex conjugates.

Methods to Find the Inverse Laplace Transform

Several techniques can be employed to determine the inverse Laplace transform:

1. Direct Recognition of Standard Forms

- Use known inverse transforms of basic functions such as (s^n) , $(\frac{1}{s})$, or $(\frac{1}{s^2})$.

2. Polynomial Decomposition and Algebraic Manipulation

- Express $(F(s))$ in terms of simpler components or as a sum/difference of known inverse transforms.

3. Using the Differentiation Property

- Exploit the property that differentiation in the (s) -domain corresponds to multiplication by (t) in the time domain, and vice versa.

4. Partial Fraction Expansion

- Break down complex rational functions into simpler fractions with known inverse transforms.

5. Applying the Inverse Laplace Transform via Complex Integration (Bromwich Integral)

- Use contour integration or residue calculus for complex functions, generally more advanced.

In our case, since $(F(s) = 4s^2 + 81)$ is a polynomial, the most straightforward approach involves recognizing its relation to derivatives and polynomial functions in the time domain.

Step-by-Step Solution to Find the Inverse Laplace Transform of $(F(s) = 4s^2 + 81)$

Let's now proceed with the detailed steps to find $(f(t) = \mathcal{L}^{-1}\{F(s)\})$.

Step 1: Break Down $(F(s))$ into Recognizable Components

$$\begin{aligned} & \mathcal{L}^{-1} \\ & F(s) = 4s^2 + 81 \\ & \end{aligned}$$

This can be viewed as:

- $(4s^2)$, which relates to derivatives of the Dirac delta function or derivatives of the inverse Laplace of basic functions.
- (81) , a constant, which corresponds to the inverse Laplace of a scaled delta or step function.

Step 2: Recall Standard Inverse Transforms

- $\mathcal{L}^{-1}\{s^n\} = \delta^{(n)}(t)$, a distribution involving derivatives of the Dirac delta, which are generalized functions often used in theoretical contexts.
- For polynomial functions, the inverse Laplace transform often involves derivatives of functions like the Dirac delta or derivatives of the Heaviside step function.

However, for practical purposes, polynomial functions in (s) typically correspond to derivatives of the Dirac delta function at $(t=0)$, which are not functions in the classical sense but generalized functions.

Step 3: Express $(F(s))$ as derivatives of simpler functions if possible

Alternatively, observe that:

$$F(s) = 4s^2 + 81$$

can be thought of as the Laplace transform of a function involving derivatives of the Dirac delta at $(t=0)$.

But in many applied contexts, especially when dealing with physical systems, the inverse Laplace transform of polynomial functions can be interpreted as derivatives of the delta function:

$$\mathcal{L}^{-1}\{s^n\} = \delta^{(n)}(t)$$

where $(\delta^{(n)}(t))$ is the (n^{th}) derivative of the delta function.

Note: The delta function and its derivatives are generalized functions (distributions), which are useful in theoretical formulations but may not be directly interpretative in all engineering contexts.

Alternative Approach: Express $(F(s))$ in Terms of Known Transforms

Given the challenges with delta functions, it's often more practical to

consider the inverse Laplace of related functions, such as:

- $\mathcal{L}^{-1}\{s\} = \delta'(t)$,
- $\mathcal{L}^{-1}\{s^2\} = \delta''(t)$,
- constants like 81 correspond to $\mathcal{L}^{-1}\{81\} = 81\delta(t)$.

However, in many engineering applications, the inverse Laplace of polynomial functions (without denominators) is understood as derivatives of the delta function at zero.

Interpreting the Result in Practical Terms

Since the inverse Laplace transform of a polynomial $\mathcal{L}^{-1}\{F(s)\}$ is a distribution involving derivatives of the delta function, the result in the classical function sense is:

$$\mathcal{L}^{-1}\{F(s)\} = 4\delta''(t) + 81\delta(t)$$

This indicates that the original time-domain function is a linear combination of the Dirac delta function and its second derivative at $t=0$. These are highly idealized mathematical constructs used primarily in theoretical analyses and are not functions in the classical sense.

Summary of the Inverse Laplace Transform of $F(s) = 4s^2 + 81$

$\mathcal{L}^{-1}\{F(s)\}$	Inverse Laplace	$\mathcal{L}^{-1}\{f(t)\}$	Interpretation
---	---	---	---
$\mathcal{L}^{-1}\{4s^2\}$	$\mathcal{L}^{-1}\{4\delta''(t)\}$	Second derivative of delta function scaled by 4	
$\mathcal{L}^{-1}\{81\}$	$\mathcal{L}^{-1}\{81\delta(t)\}$	Delta function scaled by 81	

Final Result:

$$\mathcal{L}^{-1}\{F(s)\} = 4\delta''(t) + 81\delta(t)$$

Applications and Significance of the Result

While the inverse Laplace transform involving delta functions and their derivatives may seem abstract, it plays a crucial role in various fields:

- Signal Processing: Modeling impulsive signals and their derivatives.
- Control Systems: Analyzing system responses to impulsive inputs.
- Mathematical Physics: Handling initial conditions involving derivatives.

In practical engineering problems, such as solving differential equations with impulsive initial conditions, these distributions help in understanding the system's behavior at $(t=0)$.

Conclusion and Key Takeaways

- The inverse Laplace transform of polynomial functions like $(4s^2 + 81)$ involves distributions, specifically delta functions and their derivatives.
- Recognizing the relationship between powers of (s) and derivatives of delta functions is essential.
- For classical functions, polynomial transforms typically do not correspond to ordinary functions but to generalized functions used in distribution theory.
- In applied contexts, understanding these transforms helps model impulsive phenomena and initial conditions in dynamic systems.

Additional Resources for Learning Inverse Laplace Transforms

- Textbooks:
 - "Advanced Engineering Mathematics" by Erwin Kreyszig
 - "Differential Equations and Boundary Value Problems" by Dennis G. Zill
- Online Tools:
 - Wolfram Alpha's Laplace inverse calculator
 - Symbolab and other symbolic computation platforms
- Educational Websites:
 - Khan Academy's Differential Equations section
 - Paul's Online Math Notes on Laplace Transforms

By mastering the principles outlined

Frequently Asked Questions

What is the inverse Laplace transform of $F(s) = 4s^2 / (s^2 + 81)$?

The inverse Laplace transform of $F(s) = 4s^2 / (s^2 + 81)$ is $F(t) = 4 \cos(9t)$.

How can I find the inverse Laplace transform of functions involving quadratic denominators like $s^2 + 81$?

You can decompose the function into recognizable forms such as cosine or sine transforms. For $s^2 + 81$, the inverse Laplace transform typically involves cosine or sine functions, using standard tables or partial fraction methods.

What is the significance of the constants in the function $F(s) = 4s^2 / (s^2 + 81)$ when finding the inverse Laplace transform?

Constants like 4 and the coefficients of s influence the amplitude and scaling of the resulting time-domain function, which in this case results in a scaled cosine function.

Can the inverse Laplace transform of $F(s) = 4s^2 / (s^2 + 81)$ be expressed in terms of elementary functions?

Yes, it can be expressed as $F(t) = 4 \cos(9t)$, which is an elementary trigonometric function.

What steps are involved in computing the inverse Laplace transform of $F(s) = 4s^2 / (s^2 + 81)$?

The steps include recognizing the standard Laplace pair, simplifying the expression, and applying known inverse transforms such as the cosine function for quadratic denominators, resulting in $F(t) = 4 \cos(9t)$.

Additional Resources

Find The Inverse Laplace Transform $F(t) = \mathcal{L}^{-1}\{F(s)\}$ Of The Function $F(s) = 4s^2 + 81$

Introduction: The Significance of the Inverse Laplace Transform

The inverse Laplace transform is a fundamental mathematical tool used extensively in engineering, physics, and applied mathematics. It serves as a bridge, transforming functions from the complex frequency domain (s-domain) back into the time domain (t-domain), thereby enabling the analysis of systems' behaviors over time. Whether analyzing electrical circuits, mechanical systems, or control processes, mastering the inverse Laplace transform is essential for interpreting system responses, solving differential equations, and designing stable systems.

In this article, we focus on a specific function in the s-domain, $F(s) = 4s^2 + 81$, and aim to find its inverse Laplace transform, denoted as $f(t) = \mathcal{L}^{-1}\{F(s)\}$. This exploration not only elucidates the step-by-step methodology involved but also provides insights into the broader applicability of inverse Laplace transforms in solving real-world problems.

Understanding the Given Function $F(s)$

Before delving into the inverse transformation, it is crucial to analyze the structure of the given function:

$$F(s) = 4s^2 + 81$$

This is a polynomial function in the complex variable s . Such functions often correspond to differential equations when used in the Laplace domain, and their inverse transforms typically involve derivatives of impulse functions or related elementary functions.

Key observations:

- The term $4s^2$ suggests a second-order polynomial component, which, upon inverse transformation, typically relates to derivatives of delta functions or polynomial functions in time.
- The constant term 81 indicates a shift or a constant component in the time domain, often corresponding to scaled delta functions or constants.

The overall goal is to rewrite $F(s)$ in a form that aligns with standard Laplace transform pairs, facilitating straightforward inversion.

Rewriting the Function for Ease of Inversion

To find the inverse Laplace transform, it is often helpful to express the function as a combination of simpler, well-known Laplace transform pairs.

Given:

$$F(s) = 4s^2 + 81$$

we can consider the following approach:

- Break $F(s)$ into separate terms:

$$F(s) = 4s^2 + 81$$

- Recognize that the inverse Laplace transform of s^n corresponds to derivatives of the Dirac delta function, and constants correspond to scaled delta functions. However, in many practical applications, especially in control systems, functions like s^2 relate to derivatives of the Dirac delta or to derivatives of exponential functions.

Alternatively, it's more productive to interpret $F(s)$ as the Laplace transform of a combination of functions involving derivatives of delta functions or as the sum of transforms.

But to proceed systematically, let's recall some standard Laplace transform pairs:

Function in t	Laplace Transform $F(s)$	Comments
$\delta(t)$	1	Dirac delta function
$\delta^{(n)}(t)$	s^n	n th derivative of delta
t^n	$\frac{n!}{s^{n+1}}$	Polynomial in time

Note that the direct inverse of s^2 is $\delta''(t)$, the second derivative of the delta function, which is not a typical function but a distribution.

However, in many practical contexts, especially when dealing with differential equations, the inverse Laplace transform of polynomial functions like s^2 can be associated with derivatives of the Dirac delta.

Given the above, the inverse Laplace transform of $F(s) = 4s^2 + 81$ can be expressed as a combination:

$$f(t)$$

$$F(t) = 4 \mathcal{L}^{-1}\{s^2\} + 81 \mathcal{L}^{-1}\{1\}$$

which simplifies the problem to finding the inverse transforms of these standard pairs.

Standard Inverse Laplace Transform Pairs Involved

Let's detail the key pairs relevant to this problem:

1. Inverse Laplace of $\mathcal{L}^{-1}\{1\}$:

$$\mathcal{L}^{-1}\{1\} = \delta(t)$$

where $\delta(t)$ is the Dirac delta function, representing an instantaneous impulse at $(t=0)$.

2. Inverse Laplace of $\mathcal{L}^{-1}\{s^n\}$:

$$\mathcal{L}^{-1}\{s^n\} = \delta^{(n)}(t)$$

for integer $(n \geq 0)$.

3. Inverse Laplace of $\mathcal{L}^{-1}\{1/s\}$:

$$\mathcal{L}^{-1}\left\{\frac{1}{s}\right\} = 1$$

for $(t \geq 0)$.

Given the above, the inverse Laplace transform of $(F(s))$ involves derivatives of delta functions, which are generalized functions or distributions.

Calculating the Inverse Laplace Transform of $(F(s) = 4s^2 + 81)$

Applying linearity of the inverse Laplace transform:

$$F(t) = 4 \mathcal{L}^{-1}\{s^2\} + 81 \mathcal{L}^{-1}\{1\}$$

we get:

$$F(t) = 4 \delta''(t) + 81 \delta(t)$$

Interpretation:

- $(4 \delta''(t))$ indicates a second derivative of the delta function scaled by 4, representing an impulsive acceleration or a second-order impulse at $(t=0)$.
- $(81 \delta(t))$ indicates an impulse of magnitude 81 at $(t=0)$.

This result is valid within the framework of distributions, which extend the classical functions to include generalized functions like the delta function and its derivatives.

Physical and Engineering Significance of the Result

In many engineering applications, especially in systems analysis, the inverse Laplace transform involving delta functions and their derivatives corresponds to idealized impulses and their effects. For example:

- The term $(81 \delta(t))$ can model an instantaneous pulse or force applied at $(t=0)$.
- The term $(4 \delta''(t))$ can represent an impulsive acceleration or a sudden change in the second derivative of a system's response, such as an impulsive force causing an acceleration spike.

While these are idealized mathematical constructs, they are invaluable in analyzing system responses to sudden shocks or impulses, and serve as building blocks for more complex solutions involving convolution integrals with the impulse responses.

Alternative Approaches and Broader Context

The above derivation hinges on recognizing that the polynomial $(4s^2 + 81)$ directly maps to derivatives of delta functions. However, in many practical scenarios, the functions of interest are not distributions but regular functions, and the inverse Laplace transform involves more familiar functions like exponentials, sines, cosines, or their combinations.

To explore this, consider an alternative perspective:

- Suppose $(F(s))$ were a rational function or could be expressed as a sum of simpler fractions (partial fraction decomposition). Then, the inverse transform could be obtained via standard tables.
- In this case, since $(F(s))$ is a polynomial, the inverse transform involves distributions rather than regular functions.

In summary:

- The inverse Laplace transform of $(F(s) = 4s^2 + 81)$ is $(F(t) = 4\delta''(t) + 81\delta(t))$.
- These are generalized functions that model instantaneous impulses and their derivatives.

Conclusion: Significance and Practical Implications

The process of finding the inverse Laplace transform of $(F(s) = 4s^2 + 81)$ highlights both the mathematical elegance and the practical depth of Laplace analysis. While the direct inverse involves delta functions and their derivatives—concepts from distribution theory—the core idea underscores the powerful capacity of Laplace transforms to translate complex algebraic functions into time-domain representations.

In practical engineering, such inverse transforms underpin the analysis of systems subjected to impulsive forces, shock loads, or sudden changes. Recognizing the correspondence between polynomial functions in the s -domain and their inverse distributions allows engineers and mathematicians to model, simulate, and understand transient phenomena with precision.

Furthermore, this exploration exemplifies the importance of familiarizing oneself with standard Laplace transform pairs, the utility of distribution

theory, and the necessity of interpreting generalized functions within the context of physical systems.

In essence, the inverse Laplace transform of $(F(s) = 4s^2 + 81)$ is a distribution comprising scaled derivatives of the delta function, represented as:

$$\boxed{F(t) = 4 \delta^{(2)}(t) + 81 \delta(t)}$$

This result encapsulates an instantaneous impulse and its second derivative at $(t=0)$, serving as a fundamental building block in the

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