

Use The Runge-Kutta Method With $H=0.09$ To Estimate The Value Of The Solution At $T=0.1$ To $Y' = 3 + T - Y$

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The Runge-Kutta methods are a family of iterative techniques used to approximate solutions to ordinary differential equations (ODEs). They are especially valued for their balance of accuracy and computational efficiency. In this article, we will explore how to apply the Runge-Kutta method with a step size $(h = 0.09)$ to estimate the value of the solution at $(t=0.1)$ for the differential equation:

$$\begin{aligned} & \backslash[\\ & Y' = 3 + T - Y \\ & \backslash] \end{aligned}$$

Understanding this process involves delving into the fundamentals of the Runge-Kutta methods, setting up the problem correctly, and carefully performing calculations to arrive at an accurate estimate. Let's begin by understanding the differential equation and the initial conditions.

Understanding the Differential Equation

Formulation of the Problem

The differential equation provided is:

$$\begin{aligned} & \backslash[\\ & Y' = 3 + T - Y \\ & \backslash] \end{aligned}$$

This is a first-order linear differential equation where:

- (T) represents the independent variable (often time),
- (Y) is the dependent variable (the solution function),
- (Y') is the derivative of (Y) with respect to (T) .

To solve this numerically, we need an initial condition, typically given as $(Y(t_0) = Y_0)$. Since the problem statement does not specify an initial

value, assume an initial condition at $(t=0)$, say $(Y(0) = Y_0)$, for demonstration purposes. If you have a specific initial condition, you should substitute it accordingly.

The Runge-Kutta Method: An Overview

What is the Runge-Kutta Method?

The Runge-Kutta (RK) methods are iterative procedures to solve ODEs numerically. The most commonly used is the classical fourth-order Runge-Kutta method (RK4), which offers a good balance between accuracy and computational effort.

The RK4 method estimates the solution at a point $(t + h)$ based on the current point (t) , the function $(f(t, Y))$, and multiple evaluations of (f) within the interval. It uses four slopes (k-values) to compute a weighted average, providing a higher-order approximation.

The General RK4 Formula

Given the differential equation:

$$\frac{dY}{dt} = f(t, Y)$$

and a current point (t, Y) , the RK4 method computes the next value (Y_{n+1}) as:

$$Y_{n+1} = Y_n + \frac{h}{6}(k_1 + 2k_2 + 2k_3 + k_4)$$

where:

$$\begin{aligned} k_1 &= f(t_n, Y_n) \\ k_2 &= f\left(t_n + \frac{h}{2}, Y_n + \frac{h}{2}k_1\right) \\ k_3 &= f\left(t_n + \frac{h}{2}, Y_n + \frac{h}{2}k_2\right) \\ k_4 &= f(t_n + h, Y_n + h k_3) \end{aligned}$$

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\end{aligned}  
\]
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This method involves evaluating the function $f(t, Y)$ four times per step, which ensures a fourth-order accuracy.

Applying RK4 With Step Size $(h=0.09)$

Step 1: Establish Initial Conditions

Suppose the initial condition is:

```
\[  
Y(0) = Y_0  
\]
```

For the purpose of this example, let's assume:

```
\[  
Y(0) = 2  
\]
```

This is a typical initial value used for demonstration, but you should substitute your specific initial condition if available.

Our goal is to estimate $Y(0.1)$. Since our step size is $(h=0.09)$, we will perform two steps:

1. From $(t=0)$ to $(t=0.09)$,
2. From $(t=0.09)$ to $(t=0.18)$.

However, since we want the estimate at $(t=0.1)$, which lies between (0.09) and (0.18) , we can perform a single RK4 step from $(t=0)$ to $(t=0.09)$, then interpolate or perform a smaller step to reach exactly $(t=0.1)$. Alternatively, for simplicity, we can perform a single step from (0) to (0.09) and then use a linear approximation or smaller step to estimate at $(t=0.1)$.

Step 2: Calculations for $(t=0)$ to $(t=0.09)$

Given:

$$\begin{aligned} & \backslash[\\ & f(t, Y) = 3 + t - Y \\ & \backslash] \end{aligned}$$

At $(t=0)$, $(Y=2)$:

$$\begin{aligned} & \backslash[\\ & k_1 = f(0, 2) = 3 + 0 - 2 = 1 \\ & \backslash] \end{aligned}$$

Calculate (k_2) :

$$\begin{aligned} & \backslash[\\ & k_2 = f\left(0 + \frac{h}{2}, 2 + \frac{h}{2} \times k_1 \right) = f(0.045, 2 \\ & + 0.045 \times 1) = f(0.045, 2.045) \\ & \backslash] \end{aligned}$$

$$\begin{aligned} & \backslash[\\ & k_2 = 3 + 0.045 - 2.045 = 0.995 \\ & \backslash] \end{aligned}$$

Calculate (k_3) :

$$\begin{aligned} & \backslash[\\ & k_3 = f(0.045, 2 + 0.045 \times 0.995) = f(0.045, 2 + 0.044775) = f(0.045, \\ & 2.044775) \\ & \backslash] \end{aligned}$$

$$\begin{aligned} & \backslash[\\ & k_3 = 3 + 0.045 - 2.044775 = 0.995225 \\ & \backslash] \end{aligned}$$

Calculate (k_4) :

$$\begin{aligned} & \backslash[\\ & k_4 = f(0.09, 2 + 0.09 \times 0.995225) = f(0.09, 2 + 0.089570) = f(0.09, \\ & 2.08957) \\ & \backslash] \end{aligned}$$

$$\begin{aligned} & \backslash[\\ & k_4 = 3 + 0.09 - 2.08957 = 0.99043 \\ & \backslash] \end{aligned}$$

Now, compute (Y) at $(t=0.09)$:

$$\begin{aligned} & \backslash[\\ & Y(0.09) = 2 + \frac{0.09}{6} \times (1 + 2 \times 0.995 + 2 \times 0.995225 + \\ & 0.99043) \\ & \backslash] \end{aligned}$$

Calculate the weighted sum:

$$\begin{aligned} S &= 1 + 2 \times 0.995 + 2 \times 0.995225 + 0.99043 = 1 + 1.99 + 1.99045 + \\ &0.99043 = 5.97088 \end{aligned}$$

Then:

$$Y(0.09) = 2 + 0.015 \times 5.97088 = 2 + 0.08956 \approx 2.08956$$

Step 3: Estimating Y at $t=0.1$

Since $t=0.1$ is close to $t=0.09$, we can perform a single RK4 step from $t=0.09$ to $t=0.1$ with $h=0.01$, or interpolate between the points. For better accuracy, perform a small RK4 step:

At $t=0.09$, $Y \approx 2.08956$:

Calculate k_1 :

$$k_1 = f(0.09, 2.08956) = 3 + 0.09 - 2.08956 = 0.99044$$

Calculate k_2 :

$$k_2 = f(0.09 + 0.005, 2.08956 + 0.005 \times 0.99044) = f(0.095, 2.08956 + 0.004952) = f(0.095, 2.094512)$$

$$k_2 = 3 + 0.095 - 2.094512 = 0.990488$$

Calculate k_3 :

$$k_3 = f(0.095, 2.08956 + 0.005 \times 0.990488) = f(0.095, 2.08956 + 0.004952) = 0.990488$$

Calculate k_4 :

$$k_4 = f(0.1, 2.08956 + 0.01 \times 0.990488) = f(0.1, 2.08956 + 0.00990488) =$$

$f(0)$.

Frequently Asked Questions

What is the Runge-Kutta method used for in differential equations?

The Runge-Kutta method is a numerical technique used to approximate solutions to ordinary differential equations by iteratively calculating function values at discrete steps.

How do you apply the Runge-Kutta method with step size $H=0.09$ to estimate Y at $T=0.1$?

You perform successive calculations starting from the initial condition, using $H=0.09$ to compute intermediate slopes (k-values), and then combine these to estimate Y at $T=0.1$.

What is the differential equation given in the problem?

The differential equation is $Y' = 3 + T - Y$.

What initial condition is necessary to start the Runge-Kutta method in this problem?

The initial value Y at $T=0$ is needed; typically, $Y(0)$ is provided or assumed based on the problem context.

How do you compute the first step using Runge-Kutta with $H=0.09$?

Calculate the k-values at $T=0$ using the initial Y value, then combine them to find an approximate Y at $T=0.09$.

What is the significance of choosing $H=0.09$ for this estimation?

The step size $H=0.09$ determines the granularity of the approximation; a smaller H generally yields more accurate results.

Can the Runge-Kutta method be used to estimate Y at

T=0.1 with H=0.09?

Yes, by performing two steps of size 0.09 starting from $T=0$, you can estimate Y at $T=0.18$, but for $T=0.1$, a single step or interpolation may be needed.

Is the Runge-Kutta method explicit or implicit?

The commonly used Runge-Kutta methods, including the RK4, are explicit methods.

How accurate is the Runge-Kutta method with H=0.09 for this problem?

The accuracy depends on the step size and the nature of the differential equation; generally, RK4 with $H=0.09$ provides a reasonable approximation for smooth functions.

What steps should be taken to ensure the solution at T=0.1 is accurate using H=0.09?

Perform successive Runge-Kutta steps from $T=0$ to $T=0.09$, then use the method to estimate the value at $T=0.1$, considering potential interpolation for improved accuracy.

Additional Resources

Use The Runge-Kutta Method With $H=0.09$ To Estimate The Value Of The Solution At $T=0.1$ To $Y' = 3 + T$ -

When solving differential equations numerically, the Runge-Kutta method with $H=0.09$ to estimate the value of the solution at $T=0.1$ for the differential equation $Y' = 3 + T$ - is a powerful and widely-used technique. This method offers a good balance between computational efficiency and accuracy, making it a popular choice among engineers, scientists, and mathematicians. In this guide, we'll explore how to apply the Runge-Kutta method step-by-step, understand the underlying theory, and work through a detailed example to illustrate the process.

Understanding the Differential Equation and the Numerical Approach

Before diving into the implementation, it's essential to understand the problem context and the numerical approach involved.

The Differential Equation

We are given the differential equation:

$$Y' = 3 + T - Y$$

Note: The original statement appears incomplete; it's likely intended as:

$$Y' = 3 + T - Y$$

or similar. For the sake of this guide, we will assume the differential equation is:

$$Y' = 3 + T - Y$$

This is a first-order linear differential equation. The goal is to estimate the value of Y at $T=0.1$, given that the initial condition is known at $T=0$. Assume, for simplicity, the initial condition is:

$$Y(0) = Y_0$$

Let's proceed assuming $Y(0) = 0$ (if your initial condition differs, adjust accordingly).

The Numerical Method: Runge-Kutta (RK4)

The Runge-Kutta method, particularly the classical fourth-order (RK4), is a widely used approach for solving initial value problems of the form:

$$\frac{dy}{dt} = f(t, y), \quad y(t_0) = y_0$$

The method estimates $y(t+h)$ based on four evaluations of the function f at different points within the interval.

The general RK4 formula:

$$\begin{aligned} k_1 &= h \cdot f(t_n, y_n) \\ k_2 &= h \cdot f\left(t_n + \frac{h}{2}, y_n + \frac{k_1}{2}\right) \\ k_3 &= h \cdot f\left(t_n + \frac{h}{2}, y_n + \frac{k_2}{2}\right) \\ k_4 &= h \cdot f(t_n + h, y_n + k_3) \\ y_{n+1} &= y_n + \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4) \end{aligned}$$

Step-by-Step Application: Estimating $Y(0.1)$

Step 1: Define known values

- Initial point: $t_0 = 0$
- Initial value: $y_0 = 0$ (assumed)
- Step size: $h = 0.09$

- Target point: $(T = 0.1)$

Since $(h = 0.09)$, and $(T=0.1)$, we can perform the calculation in two steps:

1. From $(t=0)$ to $(t=0.09)$
2. From $(t=0.09)$ to $(t=0.18)$

But note that (0.18) exceeds (0.1) , so to get the estimate exactly at $(t=0.1)$, we can perform an initial step with $(h=0.09)$, then a smaller step for the remaining (0.01) . Alternatively, since the step size is fixed, we can perform a single step of size (0.09) and then interpolate or adjust accordingly.

However, the problem states to use $(h=0.09)$ to estimate at $(T=0.1)$, implying a single step or a combined approach. Since the step is larger than the required (0.1) , it's easier to perform two steps:

- First step: $(t=0 \text{ to } t=0.09)$
- Second step: $(t=0.09 \text{ to } t=0.1)$

For simplicity, we can perform the first step with $(h=0.09)$, then do a smaller step of $(h=0.01)$ for the last increment, or use a modified approach. But since the instruction emphasizes using $(h=0.09)$, the most straightforward method is to perform a single step from $(t=0)$ to $(t=0.09)$, then use a modified RK4 or linear approximation to estimate the value at $(t=0.1)$.

Step 2: Calculate $(y(0.09))$ using RK4

Given $(t_0=0)$, $(y_0=0)$, and $(h=0.09)$:

1. Compute $(f(t, y) = 3 + t - y)$
2. Calculate (k_1) :

$$k_1 = h \cdot f(t_0, y_0) = 0.09 \cdot (3 + 0 - 0) = 0.09 \cdot 3 = 0.27$$

3. Calculate (k_2) :

$$k_2 = h \cdot f\left(t_0 + \frac{h}{2}, y_0 + \frac{k_1}{2}\right) = 0.09 \cdot \left(3 + 0 + \frac{0.09}{2} - \frac{0.27}{2}\right)$$

Compute the arguments:

$$t_{\text{mid}} = 0 + 0.045$$

$$y_{\text{mid}} = 0 + 0.135$$

Evaluate $f(t_{\text{mid}}, y_{\text{mid}})$:

$$f(0.045, 0.135) = 3 + 0.045 - 0.135 = 3 - 0.09 = 2.91$$

Then:

$$k_2 = 0.09 \times 2.91 = 0.2619$$

4. Calculate k_3 :

$$k_3 = 0.09 \times f\left(t_0 + \frac{h}{2}, y_0 + \frac{k_2}{2}\right)$$

$$\begin{aligned} t_{\text{mid}} &= 0.045 \\ y_{\text{mid}} &= 0 + 0.13095 \end{aligned}$$

Evaluate $f(0.045, 0.13095)$:

$$f = 3 + 0.045 - 0.13095 = 3 - 0.08595 = 2.91405$$

Then:

$$k_3 = 0.09 \times 2.91405 \approx 0.2622645$$

5. Calculate k_4 :

$$k_4 = 0.09 \times f(t_0 + h, y_0 + k_3) = 0.09 \times f(0.09, 0 + 0.2622645)$$

Calculate $f(0.09, 0.2622645)$:

$$f = 3 + 0.09 - 0.2622645 = 3.09 - 0.2622645 = 2.8277355$$

Then:

$$k_4 = 0.09 \times 2.8277355 \approx 0.2544962$$

6. Compute $y(0.09)$:

$$y_1 = y_0 + \frac{1}{6} (k_1 + 2k_2 + 2k_3 + k_4)$$

$$y_1 = 0 + \frac{1}{6} (0.27 + 2 \times 0.2619 + 2 \times 0.2622645 + 0.2544962)$$

Calculate:

$$0.27 + 0.5238 + 0.524529 + 0.2544962 = 1.5728254$$

Divide by 6:

$$y_{0.09} \approx \frac{1.5728254}{6} \approx 0.2621376$$

Step 3: Estimate $y(0.1)$

Since our step size for the first interval is 0.09, to reach 0.1, we perform a small linear approximation or a fractional RK step.

Option 1: Linear approximation:

$$\text{Estimated } y(0.1) \approx y(0.09) + (h_{\text{remaining}}) \times f(0.09, y(0.09))$$

Calculate $f(0.09, 0.2621376)$:

$$f = 3 + 0.09$$

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