

A VELOCITY VECTOR 25 BELOW THE POSITIVE X-AXIS HAS AY-COMPONENT OF -22 M/S. WHAT IS THE VALUE (IN M/S)

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UNDERSTANDING THE MAGNITUDE AND DIRECTION OF VELOCITY VECTORS IS FUNDAMENTAL IN PHYSICS, ESPECIALLY WHEN ANALYZING MOTION IN TWO DIMENSIONS. IN THIS ARTICLE, WE DELVE INTO A SPECIFIC PROBLEM INVOLVING A VELOCITY VECTOR THAT IS ORIENTED AT A CERTAIN ANGLE BELOW THE POSITIVE X-AXIS, WITH A GIVEN COMPONENT OF VELOCITY IN THE Y-DIRECTION. OUR GOAL IS TO DETERMINE THE OVERALL VELOCITY MAGNITUDE IN METERS PER SECOND (M/S). THROUGH COMPREHENSIVE EXPLANATIONS, STEP-BY-STEP CALCULATIONS, AND PRACTICAL APPLICATIONS, WE AIM TO CLARIFY HOW TO INTERPRET SUCH VECTORS AND COMPUTE THEIR MAGNITUDE ACCURATELY.

INTRODUCTION TO VELOCITY VECTORS AND THEIR COMPONENTS

BEFORE ADDRESSING THE SPECIFIC PROBLEM, IT'S ESSENTIAL TO REVIEW THE BASICS OF VELOCITY VECTORS, THEIR COMPONENTS, AND HOW THEY RELATE TO EACH OTHER.

WHAT IS A VELOCITY VECTOR?

A VELOCITY VECTOR IS A VECTOR QUANTITY THAT DESCRIBES AN OBJECT'S SPEED AND DIRECTION OF MOTION. IT IS REPRESENTED MATHEMATICALLY AS:

$$\vec{v} = v_x \hat{i} + v_y \hat{j}$$

WHERE:

- v_x IS THE COMPONENT OF VELOCITY ALONG THE X-AXIS.
- v_y IS THE COMPONENT OF VELOCITY ALONG THE Y-AXIS.
- $\hat{i}$ AND $\hat{j}$ ARE UNIT VECTORS IN THE X AND Y DIRECTIONS, RESPECTIVELY.

THE MAGNITUDE OF THE VELOCITY VECTOR, OFTEN CALLED THE SPEED, IS GIVEN BY:

$$|\vec{v}| = \sqrt{v_x^2 + v_y^2}$$

ANALYZING THE GIVEN PROBLEM

THE PROBLEM STATES:

- THE VELOCITY VECTOR IS "25 BELOW THE POSITIVE X-AXIS."
- THE Y-COMPONENT OF THE VELOCITY, v_y , IS -22 M/S.
- THE QUESTION IS: WHAT IS THE MAGNITUDE OF THE VELOCITY VECTOR IN M/S?

LET'S INTERPRET THESE DETAILS CAREFULLY.

INTERPRETING "25 BELOW THE POSITIVE X-AXIS"

THE PHRASE "25 BELOW THE POSITIVE X-AXIS" SUGGESTS THAT THE VELOCITY VECTOR FORMS AN ANGLE (θ) WITH THE POSITIVE X-AXIS, MEASURED DOWNWARD FROM THE X-AXIS. THE "BELOW" INDICATES THE VECTOR IS ORIENTED AT AN ANGLE (θ) BELOW THE HORIZONTAL (POSITIVE X-AXIS).

IN GEOMETRIC TERMS:

- THE VECTOR MAKES AN ANGLE (θ) WITH THE POSITIVE X-AXIS.
- SINCE IT'S "BELOW," (θ) IS MEASURED IN A CLOCKWISE DIRECTION FROM THE X-AXIS.
- THE MAGNITUDE OF THE VELOCITY VECTOR IS DENOTED AS $(|\vec{v}|)$.

DETERMINING THE ANGLE (θ)

THE PHRASE "25 BELOW" COMMONLY REFERS TO AN ANGLE OF 25 DEGREES MEASURED DOWNWARD FROM THE X-AXIS. THEREFORE:

$$(\theta = 25^\circ)$$

THIS ANGLE IS MEASURED FROM THE POSITIVE X-AXIS TOWARD THE NEGATIVE Y-DIRECTION (SINCE IT'S BELOW THE X-AXIS).

CALCULATING THE VELOCITY COMPONENTS

GIVEN $(|\vec{v}|)$ (UNKNOWN) AND THE ANGLE $(\theta = 25^\circ)$, THE COMPONENTS OF THE VELOCITY VECTOR ARE:

$$v_x = |\vec{v}| \cos \theta$$
$$v_y = |\vec{v}| \sin \theta$$

HOWEVER, SINCE THE VECTOR IS "BELOW" THE X-AXIS, THE Y-COMPONENT IS NEGATIVE:

$$v_y = -|\vec{v}| \sin \theta$$

FROM THE PROBLEM, WE KNOW:

$$a_y = v_y = -22 \text{ m/s}$$

SUBSTITUTING:

$$\begin{aligned} -22 &= -|\vec{v}| \sin 25^\circ \end{aligned}$$

WHICH SIMPLIFIES TO:

$$22 = |\vec{v}| \sin 25^\circ$$

SOLVING FOR THE VELOCITY MAGNITUDE

TO FIND $|\vec{v}|$, REARRANGE THE EQUATION:

$$|\vec{v}| = \frac{22}{\sin 25^\circ}$$

CALCULATING $(\sin 25^\circ)$:

$$\sin 25^\circ \approx 0.4226$$

THUS:

$$|\vec{v}| \approx \frac{22}{0.4226} \approx 52.07 \text{ m/s}$$

ANSWER: THE MAGNITUDE OF THE VELOCITY VECTOR IS APPROXIMATELY 52.07 m/s.

KEY POINTS TO REMEMBER

WHEN DEALING WITH VELOCITY VECTORS AT AN ANGLE BELOW THE X-AXIS, KEEP IN MIND:

- THE ANGLE (θ) IS MEASURED FROM THE POSITIVE X-AXIS DOWNWARD.
- THE Y-COMPONENT OF VELOCITY IS NEGATIVE IF THE VECTOR POINTS DOWNWARD.
- THE COMPONENT FORMULAS:

$$v_x = |\vec{v}| \cos \theta$$

$$v_y = -|\vec{v}| \sin \theta$$

- TO FIND THE MAGNITUDE:

$$|\vec{v}| = \sqrt{v_x^2 + v_y^2}$$

$$|\vec{v}| = \frac{|v_y|}{\sin \theta}$$

APPLICATIONS AND PRACTICAL EXAMPLES

UNDERSTANDING HOW TO ANALYZE VELOCITY VECTORS WITH KNOWN COMPONENTS IS CRUCIAL IN VARIOUS FIELDS, INCLUDING:

- AEROSPACE ENGINEERING: CALCULATING THE SPEED OF AIRCRAFT OR SPACECRAFT BASED ON COMPONENT VELOCITIES.
- NAVIGATION: DETERMINING THE ACTUAL SPEED OF A BOAT OR VEHICLE WHEN ONLY PARTIAL VELOCITY COMPONENTS ARE KNOWN.
- PHYSICS EDUCATION: SOLVING KINEMATIC PROBLEMS INVOLVING VECTORS AND ANGLES.

ADDITIONAL TIPS FOR VECTOR ANALYSIS

- ALWAYS VISUALIZE THE VECTOR WITH A DIAGRAM TO UNDERSTAND THE ORIENTATION.
- REMEMBER THAT ANGLES BELOW THE X-AXIS IMPLY NEGATIVE Y-COMPONENTS.
- USE TRIGONOMETRIC IDENTITIES CONSISTENTLY TO RESOLVE COMPONENTS.
- CONFIRM THE UNITS ARE CONSISTENT THROUGHOUT CALCULATIONS.

CONCLUSION

IN CONCLUSION, GIVEN A VELOCITY VECTOR ORIENTED 25 DEGREES BELOW THE POSITIVE X-AXIS WITH A Y-COMPONENT OF -22 M/S, THE OVERALL MAGNITUDE OF THE VELOCITY VECTOR IS APPROXIMATELY 52.07 M/S. THIS CALCULATION INVOLVES UNDERSTANDING VECTOR COMPONENTS, INTERPRETING ANGLES CORRECTLY, AND APPLYING BASIC TRIGONOMETRY. MASTERY OF THESE CONCEPTS ENABLES PRECISE ANALYSIS OF MOTION IN TWO DIMENSIONS, ESSENTIAL FOR PHYSICS PROBLEMS, ENGINEERING APPLICATIONS, AND REAL-WORLD NAVIGATION.

WHETHER YOU'RE STUDYING PHYSICS, WORKING ON ENGINEERING PROBLEMS, OR JUST KEEN TO DEEPEN YOUR UNDERSTANDING OF VECTOR ANALYSIS, GRASPING HOW TO COMPUTE THE MAGNITUDE OF A VELOCITY VECTOR FROM ITS COMPONENTS IS A FUNDAMENTAL SKILL. KEEP PRACTICING WITH DIFFERENT ANGLES AND COMPONENT VALUES TO STRENGTHEN YOUR PROFICIENCY IN VECTOR MATHEMATICS AND MOTION ANALYSIS.

KEYWORDS: VELOCITY VECTOR, VECTOR COMPONENTS, MAGNITUDE OF VELOCITY, TRIGONOMETRY IN PHYSICS, MOTION ANALYSIS, VELOCITY COMPONENTS CALCULATION, VECTOR ANGLE BELOW X-AXIS, SOLVING FOR VELOCITY MAGNITUDE, PHYSICS PROBLEM-SOLVING

FREQUENTLY ASKED QUESTIONS

WHAT IS THE VELOCITY VECTOR'S COMPONENT ALONG THE Y-AXIS IF IT IS 25 M/S

BELOW THE POSITIVE X-AXIS WITH A Y-COMPONENT OF -22 M/S?

THE Y-COMPONENT OF THE VELOCITY VECTOR IS -22 M/S, INDICATING IT POINTS DOWNWARD.

HOW DO YOU DETERMINE THE MAGNITUDE OF A VELOCITY VECTOR GIVEN ITS COMPONENTS?

THE MAGNITUDE IS FOUND USING PYTHAGORAS' THEOREM: $\sqrt{V_x^2 + V_y^2}$.

GIVEN A VELOCITY VECTOR WITH A Y-COMPONENT OF -22 M/S, WHAT ADDITIONAL INFORMATION IS NEEDED TO FIND ITS TOTAL SPEED?

THE X-COMPONENT OF THE VELOCITY VECTOR IS NEEDED TO CALCULATE THE TOTAL SPEED.

IF A VELOCITY VECTOR IS 25 M/S BELOW THE POSITIVE X-AXIS AND HAS A Y-COMPONENT OF -22 M/S, WHAT IS THE APPROXIMATE MAGNITUDE OF THE VELOCITY?

THE MAGNITUDE IS APPROXIMATELY $\sqrt{V_x^2 + (-22)^2}$ M/S; IF V_x IS KNOWN, PLUG IN TO FIND THE TOTAL SPEED.

WHY IS THE Y-COMPONENT OF THE VELOCITY VECTOR NEGATIVE IN THIS SCENARIO?

BECAUSE THE VELOCITY VECTOR POINTS BELOW THE POSITIVE X-AXIS, INDICATING DOWNWARD DIRECTION, WHICH IS REPRESENTED BY A NEGATIVE Y-COMPONENT.

ADDITIONAL RESOURCES

UNDERSTANDING THE VELOCITY VECTOR AND ITS COMPONENTS: A COMPREHENSIVE ANALYSIS

WHEN EXPLORING CONCEPTS IN PHYSICS, PARTICULARLY IN KINEMATICS, VECTORS PLAY A VITAL ROLE IN DESCRIBING MOTION. THE VELOCITY VECTOR, WHICH INDICATES BOTH THE SPEED AND DIRECTION OF AN OBJECT, CAN BE DISSECTED INTO ITS COMPONENTS ALONG THE COORDINATE AXES. GRASPING HOW TO ANALYZE AND INTERPRET THESE COMPONENTS IS ESSENTIAL FOR SOLVING A WIDE ARRAY OF PROBLEMS, INCLUDING THOSE INVOLVING VECTOR DIRECTIONS, MAGNITUDES, AND THEIR RELATIONSHIPS.

IN THIS DETAILED REVIEW, WE WILL EXAMINE THE SPECIFIC PROBLEM:

"A VELOCITY VECTOR 25 M/S BELOW THE POSITIVE X-AXIS HAS A Y-COMPONENT OF -22 M/S. WHAT IS THE VALUE (IN M/S)?"

THIS QUESTION INVOLVES UNDERSTANDING VECTOR DIRECTIONS, COMPONENTS, AND HOW TO DERIVE THE MAGNITUDE OF THE VELOCITY VECTOR BASED ON GIVEN INFORMATION. WE WILL EXPLORE THE UNDERLYING CONCEPTS SYSTEMATICALLY, PROVIDING CLARITY ON THE PHYSICS PRINCIPLES INVOLVED.

FUNDAMENTALS OF VELOCITY VECTORS AND COMPONENTS

WHAT IS A VELOCITY VECTOR?

A VELOCITY VECTOR, OFTEN REPRESENTED AS $\vec{v}$, ENCAPSULATES BOTH THE MAGNITUDE (SPEED) AND DIRECTION OF AN OBJECT'S MOTION. UNLIKE SCALAR SPEED, WHICH ONLY INDICATES HOW FAST AN OBJECT MOVES, THE VELOCITY VECTOR

PROVIDES A COMPLETE DESCRIPTION OF MOTION IN A COORDINATE SYSTEM.

MATHEMATICALLY, IN TWO DIMENSIONS:

$$\vec{v} = v_x \hat{i} + v_y \hat{j}$$

WHERE:

- v_x IS THE COMPONENT OF VELOCITY ALONG THE X-AXIS,
- v_y IS THE COMPONENT ALONG THE Y-AXIS,
- $\hat{i}$ AND $\hat{j}$ ARE THE UNIT VECTORS IN THE X AND Y DIRECTIONS, RESPECTIVELY.

COMPONENTS OF VELOCITY AND THEIR SIGNIFICANCE

THE COMPONENTS v_x AND v_y DEFINE THE VECTOR'S DIRECTION AND MAGNITUDE:

- THE MAGNITUDE (OR SPEED) IS GIVEN BY:

$$|\vec{v}| = \sqrt{v_x^2 + v_y^2}$$

- THE DIRECTION CAN BE DESCRIBED USING THE ANGLE θ RELATIVE TO THE POSITIVE X-AXIS:

$$\theta = \arctan\left(\frac{v_y}{v_x}\right)$$

UNDERSTANDING THE SIGN CONVENTIONS:

- A POSITIVE v_x INDICATES MOTION IN THE POSITIVE X-DIRECTION.
- A NEGATIVE v_x INDICATES MOTION IN THE NEGATIVE X-DIRECTION.
- SIMILARLY FOR v_y .

DECIPHERING THE PROBLEM STATEMENT

LET'S ANALYZE THE GIVEN PROBLEM CAREFULLY:

"A VELOCITY VECTOR 25 M/S BELOW THE POSITIVE X-AXIS HAS A Y-COMPONENT OF -22 M/S. WHAT IS THE MAGNITUDE OF THE VELOCITY?"

KEY POINTS:

- THE VECTOR IS "BELOW THE POSITIVE X-AXIS," INDICATING A SPECIFIC DIRECTION.
- THE MAGNITUDE OF THE VELOCITY VECTOR IS 25 M/S.
- THE COMPONENT ALONG THE Y-AXIS (v_y) IS -22 M/S.

INTERPRETING THE DIRECTION: "BELOW THE POSITIVE X-AXIS"

THE PHRASE "BELOW THE POSITIVE X-AXIS" DESCRIBES THE VECTOR'S ORIENTATION IN THE COORDINATE PLANE:

- THE POSITIVE X-AXIS POINTS TO THE RIGHT.
- MOVING "BELOW" THE POSITIVE X-AXIS IMPLIES A DIRECTION INCLINED DOWNWARD FROM THE X-AXIS.

IN STANDARD CARTESIAN COORDINATE SYSTEMS:

- THE VECTOR POINTS IN THE FOURTH QUADRANT, WHERE:
- $(v_x > 0)$
- $(v_y < 0)$

THE PHRASE "BELOW" IS OFTEN ASSOCIATED WITH A NEGATIVE Y-COMPONENT WHEN REFERENCED RELATIVE TO THE X-AXIS.

GIVEN DATA SUMMARY

- MAGNITUDE OF VELOCITY: $(|\vec{v}| = 25, \text{m/s})$
- $(v_y = a_y = -22, \text{m/s})$

NOTE THAT THE PROBLEM EXPLICITLY STATES THE Y-COMPONENT, BUT NOT THE X-COMPONENT. THE QUESTION ASKS: "WHAT IS THE VALUE (IN M/S)?"

GIVEN THE CONTEXT, THIS IS MOST LIKELY ASKING FOR THE MAGNITUDE OF THE VELOCITY VECTOR, WHICH IS GIVEN AS 25 M/S, OR PERHAPS THE X-COMPONENT.

GIVEN THE WORDING, IT SEEMS THE PROBLEM IS DESIGNED TO TEST UNDERSTANDING OF VECTOR COMPONENTS AND THEIR RELATIONSHIP TO THE MAGNITUDE.

CALCULATING THE VELOCITY COMPONENTS AND MAGNITUDE

STEP 1: RECOGNIZE THE KNOWN QUANTITIES

- MAGNITUDE: $(|\vec{v}| = 25, \text{m/s})$
- Y-COMPONENT: $(v_y = -22, \text{m/s})$

STEP 2: USE THE PYTHAGOREAN THEOREM TO FIND THE X-COMPONENT

SINCE THE VELOCITY VECTOR'S MAGNITUDE AND Y-COMPONENT ARE KNOWN, THE X-COMPONENT (v_x) CAN BE FOUND FROM:

$$|\vec{v}|^2 = v_x^2 + v_y^2$$

SUBSTITUTING KNOWN QUANTITIES:

$$25^2 = v_x^2 + (-22)^2$$

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$$625 = v_x^2 + 484$$

$$v_x^2 = 625 - 484 = 141$$

$$v_x = \pm \sqrt{141} \approx \pm 11.87, \text{ m/s}$$

THE SIGN OF (v_x) DEPENDS ON THE CONTEXT:

- SINCE THE VECTOR IS "BELOW THE POSITIVE X-AXIS," AND THE Y-COMPONENT IS NEGATIVE, THE ANGLE IS IN THE FOURTH QUADRANT.
- IN THE FOURTH QUADRANT, $(v_x > 0)$.

THEREFORE:

$$v_x \approx +11.87, \text{ m/s}$$

STEP 3: CONFIRM THE MAGNITUDE AND DIRECTION

CALCULATE THE MAGNITUDE:

$$|\vec{v}| = \sqrt{v_x^2 + v_y^2} = \sqrt{(11.87)^2 + (-22)^2} \approx \sqrt{141 + 484} = \sqrt{625} = 25, \text{ m/s}$$

THIS CONFIRMS OUR CALCULATIONS ARE CONSISTENT WITH THE GIVEN MAGNITUDE, AND THE VECTOR POINTS AT AN ANGLE (θ) SUCH THAT:

$$\theta = \arctan\left(\frac{v_y}{v_x}\right) = \arctan\left(\frac{-22}{11.87}\right) \approx \arctan(-1.855) \approx -61.8^\circ$$

THE NEGATIVE ANGLE INDICATES THAT THE VECTOR IS INCLINED DOWNWARD FROM THE X-AXIS, CONSISTENT WITH THE "BELOW" DESCRIPTION.

UNDERSTANDING THE SIGNIFICANCE OF COMPONENTS AND DIRECTION

QUADRANT IDENTIFICATION

BASED ON OUR CALCULATIONS:

- $(v_x \approx +11.87, \text{m/s})$
- $(v_y = -22, \text{m/s})$

THE VECTOR IS IN THE FOURTH QUADRANT, WHERE:

- X-COMPONENT IS POSITIVE.
- Y-COMPONENT IS NEGATIVE.

THIS MATCHES THE PHRASE "BELOW THE POSITIVE X-AXIS," AS THE VECTOR POINTS DOWNWARD AND TO THE RIGHT.

IMPLICATIONS FOR MOTION AND ANALYSIS

KNOWING THE COMPONENTS ALLOWS US TO:

- DETERMINE THE EXACT DIRECTION OF THE VELOCITY VECTOR.
- CALCULATE THE ANGLE OF MOTION RELATIVE TO THE X-AXIS.
- ANALYZE HOW THE OBJECT MOVES IN THE PLANE.

THESE COMPONENTS ARE ESSENTIAL FOR RESOLVING PROBLEMS INVOLVING:

- RELATIVE MOTION.
- ACCELERATION COMPONENTS.
- FORCE ANALYSIS IF FORCES ARE APPLIED ALONG SPECIFIC AXES.

ADDITIONAL CONSIDERATIONS AND PRACTICAL APPLICATIONS

VECTOR RESOLUTION IN REAL-WORLD CONTEXTS

IN REAL-WORLD PHYSICS AND ENGINEERING SCENARIOS:

- RESOLVING VECTORS INTO COMPONENTS HELPS DESIGN TRAJECTORIES.
- ANALYZING THE EFFECTS OF DIFFERENT FORCES.
- PLANNING NAVIGATION PATHS.

FOR EXAMPLE, IN AEROSPACE ENGINEERING, KNOWING THE VELOCITY COMPONENTS HELPS IN COURSE CORRECTION. IN ROBOTICS, PRECISE COMPONENT ANALYSIS ENSURES ACCURATE MOTION CONTROL.

VECTOR DIRECTION IN DIFFERENT QUADRANTS

- FIRST QUADRANT: $(v_x > 0, v_y > 0)$
- SECOND QUADRANT: $(v_x < 0, v_y > 0)$
- THIRD QUADRANT: $(v_x < 0, v_y < 0)$
- FOURTH QUADRANT: $(v_x > 0, v_y < 0)$

THE PROBLEM'S VECTOR RESIDES IN THE FOURTH QUADRANT, CONSISTENT WITH THE NEGATIVE Y-COMPONENT AND POSITIVE X-

COMPONENT.

CONCLUSION: FINAL ANSWER AND SUMMARY

FROM THE ANALYSIS:

- THE VELOCITY VECTOR HAS A MAGNITUDE OF 25 M/S.
- THE Y-COMPONENT, $\backslash(v_y\backslash)$, IS -22 M/S.
- THE X-COMPONENT, $\backslash(v_x\backslash)$, IS APPROXIMATELY +11.87 M/S.

THEREFORE, THE VALUE OF THE VELOCITY VECTOR IN THE CONTEXT OF THIS PROBLEM IS 25 M/S, WHICH MATCHES THE GIVEN MAGNITUDE, AND THE COMPONENTS ARE CONSISTENT WITH THE DESCRIBED DIRECTION.

KEY TAKEAWAYS

- UNDERSTANDING VECTOR COMPONENTS IS FUNDAMENTAL TO ANALYZING MOTION.
- THE DIRECTION "BELOW THE POSITIVE X-AXIS" INDICATES A VECTOR IN THE FOURTH QUADRANT.
- USING THE PYTHAGOREAN THEOREM ALLOWS CALCULATION OF UNKNOWN COMPONENTS WHEN MAGNITUDE AND ONE COMPONENT ARE KNOWN.
- SIGN CONVENTIONS ARE CRUCIAL FOR ACCURATE INTERPRETATION OF VECTOR DIRECTIONS.
- REAL-WORLD APPLICATIONS OF VECTOR ANALYSIS ARE DIVERSE, SPANNING NAVIGATION, ENGINEERING, AND PHYSICS.

IN SUMMARY, THE PROBLEM EXEMPLIFIES FUNDAMENTAL PRINCIPLES OF VECTOR

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