

The Velocity V Of A Particle Moving In The xy Plane Is Given By $V = (6t - 4t^2) \mathbf{i} + 1\mathbf{j}$. Here V Is

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Understanding the motion of particles in the xy -plane is fundamental in physics and engineering. The velocity vector provides crucial insights into the particle's speed and direction at any given time. When the velocity is expressed in a form such as $V = (6t - 4t^2) \mathbf{i} + 1\mathbf{j}$, it encapsulates both magnitude and direction as functions of time, offering a detailed picture of the particle's dynamics. This article explores this velocity expression comprehensively, breaking down its components, analyzing its implications, and discussing related concepts to enhance understanding.

Breaking Down the Velocity Expression

The given velocity vector is:

$$V(t) = (6t - 4t^2) \mathbf{i} + 1\mathbf{j}$$

This notation involves complex numbers to represent the velocity components, which is common in physics for simplifying two-dimensional vector calculations.

Understanding the Components

- $\mathbf{i}$: Represents the unit vector in the x -direction, i.e., $\mathbf{i} = \hat{i}$.
- $1\mathbf{j}$: Represents the unit vector in the y -direction, i.e., $\hat{j}$.

Thus, the velocity vector can be written explicitly as:

$$V(t) = [(6t - 4t^2) \hat{i}] + (1 \hat{j})$$

or

$$V(t) = (6t - 4t^2) \hat{i} + \hat{j}$$

This form clearly shows the x -component and y -component of the velocity at any time t .

Interpreting the Components

- X-component (V_x): $(6t - 4t^2)$
- Y-component (V_y): 1

The x-component varies with time, while the y-component remains constant. This indicates that the particle's horizontal motion changes over time, but its vertical velocity remains steady.

Analyzing the Particle's Velocity Over Time

Understanding how the velocity components evolve helps us analyze the particle's trajectory, speed, and acceleration.

Velocity in the X-Direction (V_x)

The x-component $V_x = 6t - 4t^2$ is a quadratic function of time.

- At $t=0$, $V_x=0$.
- The function reaches a maximum at $t = (6)/(8) = 0.75$ seconds.
- For $t > 0.75$, V_x decreases and eventually becomes negative, indicating a change in direction along the x-axis.

Calculating the maximum x-velocity:

$$V_x(t) = 6t - 4t^2$$

To find the maximum, take the derivative:

$$dV_x/dt = 6 - 8t$$

Set to zero:

$$6 - 8t = 0$$

$$t = 6/8 = 0.75 \text{ seconds}$$

Maximum V_x :

$$V_x(0.75) = 6(0.75) - 4(0.75)^2 = 4.5 - 4(0.5625) = 4.5 - 2.25 = 2.25 \text{ units/sec}$$

Velocity in the Y-Direction (V_y)

V_y is constant:

$$V_y = 1 \text{ units/sec}$$

This means the particle moves upward at a constant speed throughout its motion.

Speed and Magnitude of Velocity

The magnitude of the velocity vector, denoted as $V(t)$, can be calculated using the Pythagorean theorem:

$$V(t) = \sqrt{V_x(t)^2 + V_y^2}$$

Substituting:

$$V(t) = \sqrt{(6t - 4t^2)^2 + 1^2}$$

Expanding:

$$V(t) = \sqrt{(36t^2 - 48t^3 + 16t^4) + 1}$$

This expression allows calculation of the particle's speed at any time t .

Graphical Interpretation

Plotting V_x vs. time shows a parabola opening downward with a peak at $t=0.75$ sec. Since V_y is constant, the overall velocity magnitude will have a varying shape, influenced mainly by V_x .

Determining the Particle's Trajectory

The velocity vector provides the rate of change of position. To find the actual path, we need to integrate the velocity components over time.

Position Components

- X-position ($x(t)$):

$$x(t) = \int V_x dt + x_0$$

- Y-position ($y(t)$):

$$y(t) = \int V_y dt + y_0$$

Assuming initial positions $x_0=0$ and $y_0=0$, then:

$$x(t) = \int (6t - 4t^2) dt = 3t^2 - (4/3)t^3 + Cx$$

$$x(0) = 0, \text{ so } Cx=0$$

$$x(t) = 3t^2 - (4/3)t^3$$

Similarly,

$$y(t) = \int 1 dt = t + Cy$$

$$\text{Assuming } y(0)=0, Cy=0$$

$$y(t) = t$$

Resulting Trajectory Equation:

$$\text{Express } y \text{ in terms of } t: y(t) = t$$

Express x in terms of y :

$$x(y) = 3y^2 - (4/3)y^3$$

This provides the particle's path in the xy -plane.

Physical Significance and Applications

The analysis of such velocity expressions has multifaceted applications:

1. Projectile Motion Analysis

- Understanding how particles move under various velocity components.
- Designing trajectories in engineering applications, such as missile guidance or sports physics.

2. Robotics and Autonomous Vehicles

- Planning paths based on velocity profiles.
- Ensuring smooth motion with changing velocity components.

3. Physics and Kinematics Education

- Teaching concepts of velocity, acceleration, and trajectory through real-world examples.

Acceleration Analysis

While the focus is on velocity, acceleration provides further insight into the particle's motion.

Calculating Acceleration Components

- $A_x(t)$:

$$a_x = dV_x/dt = 6 - 8t$$

- A_y :

$$a_y = dV_y/dt = 0 \text{ (constant)}$$

The acceleration vector:

$$a(t) = (6 - 8t) \hat{i} + 0\hat{j}$$

This indicates that the particle experiences a time-dependent horizontal acceleration, while the vertical acceleration is zero.

Implications of Acceleration

- The negative acceleration after $t=0.75$ sec causes the x-component of velocity to decrease.
- The particle's motion transitions from moving forward to slowing down and possibly reversing direction along the x-axis.

Summary and Key Takeaways

- The velocity vector $V = (6t - 4t^2) \hat{i} + 1\hat{j}$ describes a particle moving in the xy-plane with a time-dependent x-component and a constant y-component.
- The x-velocity reaches a maximum of 2.25 units/sec at $t=0.75$ sec and then decreases.
- The y-component remains constant at 1 unit/sec, indicating uniform vertical motion.
- The particle's position over time can be derived by integrating the velocity components, resulting in explicit equations for $x(t)$ and $y(t)$.
- The overall speed varies over time, influenced primarily by the quadratic

x-component of velocity.

- Acceleration analysis reveals a changing horizontal acceleration, impacting the particle's trajectory.

Final Thoughts

Understanding complex velocity expressions like $V = (6t - 4t^2) \mathbf{i} + 1\mathbf{j}$ is essential for analyzing real-world motion scenarios. Whether in physics education, engineering design, or robotics, such detailed breakdowns enable accurate modeling of particle trajectories and motion behaviors. By mastering these concepts, students and professionals can better predict, control, and optimize movement in various applications, from simple projectile physics to complex autonomous navigation systems.

Keywords: velocity in xy-plane, particle motion, velocity components, trajectory analysis, acceleration, kinematics, physics, engineering, complex vectors, motion analysis

Frequently Asked Questions

What is the expression for the velocity V of the particle in the xy-plane?

The velocity V is given by $V = (6t - 4t^2) \mathbf{i} + 1\mathbf{j}$, where $\mathbf{i}$ and $\mathbf{j}$ are the unit vectors in the x and y directions respectively.

How do you interpret the velocity function $V = (6t - 4t^2) \mathbf{i} + 1\mathbf{j}$?

This function describes a particle whose x-component of velocity varies with time as $(6t - 4t^2)$, while the y-component remains constant at 1 unit per time.

What is the magnitude of the velocity vector V at time t ?

The magnitude is given by $|V| = \sqrt{(6t - 4t^2)^2 + (1)^2}$.

At what time t does the particle have zero velocity in the x-direction?

Set $(6t - 4t^2) = 0$, which gives $t = 0$ and $t = 1$. The velocity in the x-direction is zero at $t = 0$ and $t = 1$.

What is the acceleration of the particle in the xy-plane?

The acceleration is the derivative of velocity with respect to time: $a = dV/dt = (6 - 8t) \mathbf{i} + 0\mathbf{j}$.

At what time t is the particle's velocity maximum in the x-direction?

Since the x-component of velocity is $(6t - 4t^2)$, it reaches its maximum when its derivative with respect to t is zero: $d/dt (6t - 4t^2) = 6 - 8t = 0$, giving $t = 0.75$.

How do you find the trajectory of the particle given its velocity V ?

Integrate the velocity components with respect to time to obtain position functions $x(t)$ and $y(t)$.

What is the physical significance of the constant y-component of velocity being $1\mathbf{j}$?

It indicates that the particle moves upward (or in the positive y-direction) at a constant velocity of 1 unit per time, unaffected by the x-component.

How can we determine when the particle changes direction in the x-axis?

The particle changes direction in x when the x-velocity component $(6t - 4t^2)$ changes sign, i.e., at $t = 0$ and $t = 1$.

What are the key characteristics of the particle's motion based on the given velocity?

The particle moves with a time-dependent velocity in the x-direction, reaching maximum speed at $t = 0.75$, and maintains a constant y-direction velocity of 1. It accelerates and decelerates in x according to the velocity function, with potential changes in direction at specific times.

Additional Resources

The Velocity V of a Particle Moving in the XY Plane Is Given by $V = (6t - 4t^2) \mathbf{i} + 1\mathbf{j}$. Here V Is

Understanding the motion of particles in the plane is a fundamental aspect of classical mechanics, providing insights into the dynamics that govern

everyday phenomena and complex systems alike. The velocity vector, in particular, encapsulates crucial information about the speed and direction of a particle at any given instant. In this context, the expression $V = (6t - 4t^2) \mathbf{i} + 1\mathbf{j}$ introduces a specific case where the velocity depends on time in a nuanced manner, combining a quadratic term with a constant component. This article delves deep into this velocity expression, exploring its implications, derivations, and significance through a structured, detailed analysis.

Understanding the Given Velocity Expression

Decomposition of the Velocity Vector

The velocity vector V is expressed as:

$$V(t) = (6t - 4t^2) \mathbf{i} + 1\mathbf{j}$$

Breaking this down:

- The x-component of velocity, $V_x(t) = 6t - 4t^2$
- The y-component of velocity, $V_y(t) = 1$

This indicates that at any instant t , the particle's velocity in the x-direction varies quadratically with time, while the velocity in the y-direction remains constant.

Physical Significance of Components

- X-component (V_x): The quadratic form suggests an initial increase in velocity in the x-direction, reaching a maximum, followed by a decrease. This is typical in scenarios where acceleration is not constant but varies with time.
- Y-component (V_y): The constant value implies uniform motion along the y-axis, unaffected by the particle's position or the influence of any force that might vary with time.

Mathematical Foundations and Derivations

Analyzing the Velocity Function

The velocity function's structure allows us to derive several key kinematic quantities:

- Magnitude (Speed): The scalar speed $V(t)$ is obtained by taking the magnitude of the velocity vector:

$$V(t) = \sqrt{V_x(t)^2 + V_y(t)^2}$$

- Direction: The direction of motion can be described by the angle $\theta(t)$ the velocity vector makes with the positive x-axis:

$$\theta(t) = \arctangent [V_y(t) / V_x(t)] = \arctangent [1 / (6t - 4t^2)]$$

Calculating the Speed

Speed at any time t :

$$\begin{aligned} V(t) &= \sqrt{(6t - 4t^2)^2 + 1^2} \\ &= \sqrt{(36t^2 - 48t^3 + 16t^4) + 1} \end{aligned}$$

This expression reveals how the particle's instantaneous speed varies with time, influenced predominantly by the quadratic term in $V_x(t)$.

Direction of Motion

The angle $\theta(t)$:

$$\theta(t) = \arctangent [1 / (6t - 4t^2)]$$

- For values of t where $V_x(t) > 0$, $\theta(t)$ is positive, indicating motion oriented in a particular direction.
- When $V_x(t) = 0$, the particle is moving purely in the y-direction.
- When $V_x(t) < 0$, the angle becomes negative or adjusts accordingly, indicating a change in the direction of the x-component.

Time Behavior and Critical Points

When Does the Velocity in X-Component Maximize?

Given $V_x(t) = 6t - 4t^2$, its maximum occurs where its derivative with respect to time is zero:

$$\begin{aligned} dV_x/dt &= 6 - 8t = 0 \\ \Rightarrow t &= 6/8 = 0.75 \text{ seconds} \end{aligned}$$

At $t = 0.75$ seconds, the particle has its maximum x-velocity of:

$$\begin{aligned} V_x(0.75) &= 6(0.75) - 4(0.75)^2 = 4.5 - 4(0.5625) = 4.5 - 2.25 = 2.25 \\ &\text{units/sec} \end{aligned}$$

This point signifies the peak in the x-direction speed, after which the x-velocity diminishes, eventually becoming negative, indicating motion reversal along the x-axis.

Zero X-Component and Changes in Direction

$V_x(t) = 0$ when:

$$\begin{aligned} 6t - 4t^2 &= 0 \\ t(6 - 4t) &= 0 \\ \Rightarrow t &= 0 \text{ or } t = 6/4 = 1.5 \text{ seconds} \end{aligned}$$

- At $t=0$, the initial velocity is zero, indicating the particle starts from rest.
- At $t=1.5$ seconds, V_x becomes zero again, marking a change in the direction of the x-component.

Between $t=0$ and $t=1.5$ seconds, $V_x > 0$; after $t=1.5$ seconds, $V_x < 0$, indicating the particle reverses its x-direction of motion.

Position and Trajectory Analysis

Integrating Velocity to Find Position

To understand the particle's path, we integrate the velocity components over time:

- Position in x-direction:

$$x(t) = x_0 + \int V_x(t) dt$$

- Position in y-direction:

$$y(t) = y_0 + \int V_y dt = y_0 + t \text{ (since } V_y \text{ is constant)}$$

Assuming initial positions x_0 and y_0 are zero for simplicity:

$$x(t) = \int (6t - 4t^2) dt = 3t^2 - (4/3)t^3 + C_x$$

$$y(t) = t + C_y$$

Taking initial positions as zero:

$$x(t) = 3t^2 - (4/3)t^3$$

$$y(t) = t$$

This parametric form describes the particle's trajectory in the XY-plane.

Trajectory Characteristics

Plotting $x(t)$ versus $y(t)$:

- The path is governed by a polynomial relation between x and y .
- The particle exhibits a curved trajectory, initially moving forward along the x -axis, reaching a peak, then reversing, with a steady upward motion in y .

The shape of the trajectory depends on the interplay between the quadratic and linear terms, producing a curve that could resemble a parabola or more complex path, depending on the parameter t .

Acceleration and Dynamics

Deriving Acceleration Components

Acceleration is the rate of change of velocity. Differentiating $V_x(t)$:

$$a_x(t) = dV_x/dt = 6 - 8t$$

$$a_y(t) = dV_y/dt = 0 \text{ (since } V_y \text{ is constant)}$$

- At $t=0$, $a_x = 6 \text{ units/sec}^2$, indicating initial acceleration in the x-direction.
- At $t=0.75$, $a_x = 0$, corresponding to the maximum V_x .
- For $t > 0.75$, a_x becomes negative, indicating deceleration in the x-direction.

In the y-direction, acceleration is zero, confirming uniform motion in y.

Implications for Particle Motion

- The particle accelerates in the x-direction initially, then decelerates, reverses direction, and continues to accelerate negatively afterward.
- The y-component of motion is uniform, meaning no acceleration acts in y, and the particle moves steadily upward.

Physical Context and Practical Applications

Relevance in Real-World Scenarios

Expressions like $V = (6t - 4t^2) \mathbf{i} + 1\mathbf{j}$ are instrumental in modeling phenomena where acceleration varies with time:

- Projectile motion with air resistance: Where drag introduces non-constant acceleration.
- Particle dynamics in fields: For example, charged particles in electromagnetic fields where forces change over time.
- Robotics and automation: Path planning where velocity profiles are designed for specific tasks.

Implications for Engineering and Physics

Understanding such velocity profiles aids in:

- Designing trajectories with specific dynamic properties.
- Analyzing stability and control in mechanical systems.
- Developing simulations for complex motion patterns.

Conclusion and Final Remarks

The velocity vector $V = (6t - 4t^2) \mathbf{i} + 1\mathbf{j}$ embodies a rich tapestry of kinematic phenomena. Its quadratic x-component introduces dynamic acceleration and deceleration phases, with critical points where the velocity peaks or reverses direction. The constant y-component simplifies the analysis in that dimension, providing a steady upward motion. By integrating these velocity components, one can reconstruct the particle's entire trajectory, revealing a curved path that encapsulates the interplay of acceleration, velocity, and position.

This detailed exploration underscores the importance of mathematical tools in dissecting motion, offering insights that extend beyond theoretical exercises to practical applications across physics, engineering, and related fields. The nuanced behavior captured by such an expression exemplifies how complex motion can be succinctly described and thoroughly understood through systematic analysis.

In essence, the velocity expression $V = (6t - 4t^2) \mathbf{i} + 1\mathbf{j}$ serves as a window into the intricate dance of particles under varying forces, highlighting the elegance and utility of classical mechanics in decoding the universe's dynamical tapestry.

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