

Determine Whether Or Not The Indicated Set Of 3 3 Matrices Is A Subspace Of M_{33} . The Set Of All Symmetric

Determine Whether Or Not The Indicated Set Of 3 x 3 Matrices Is A Subspace Of M_{33} . The Set Of All Symmetric

When studying vector spaces, one fundamental question is whether a particular subset qualifies as a subspace. In the context of matrices, especially 3 x 3 matrices, determining if a subset forms a subspace involves verifying certain properties. This article explores the criteria for subspaces within the space of all 3 x 3 matrices, denoted as M_{33} , with specific focus on the set of all symmetric matrices. We will analyze the characteristics that define symmetric matrices, examine the conditions for subspaces, and ultimately determine whether the set of symmetric matrices constitutes a subspace of M_{33} .

Understanding Matrix Spaces and Subspaces

What Is M_{33} ?

M_{33} is the vector space consisting of all 3 x 3 matrices with real entries. Each element of M_{33} can be written as:

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

where each $a_{ij} \in \mathbb{R}$.

What Is a Subspace?

A subset W of a vector space V is a subspace if it satisfies three fundamental properties:

1. Zero Vector Inclusion: The zero vector of V is in W .
2. Closed Under Addition: For all $u, v \in W$, the sum $u + v$ is also in W .
3. Closed Under Scalar Multiplication: For all $u \in W$ and scalar $c \in \mathbb{R}$, the product $c u$ is in W .

In the context of matrices, these properties translate to:

- The zero matrix must be in the set.
- The sum of any two matrices in the set must also be in the set.
- Multiplying any matrix in the set by a scalar must result in a matrix still within the set.

Defining the Set of All Symmetric Matrices

What Are Symmetric Matrices?

A matrix $A \in M_{3 \times 3}$ is symmetric if it equals its transpose:

$$A = A^T$$

Explicitly, for a 3 x 3 matrix:

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

being symmetric requires:

$$a_{12} = a_{21}, \quad a_{13} = a_{31}, \quad a_{23} = a_{32}$$

and the diagonal entries are unrestricted.

Properties of Symmetric Matrices

- All diagonal elements are real numbers.
- Off-diagonal elements are mirrored across the main diagonal.
- The set of all symmetric matrices in M_{33} is denoted as $\mathcal{S}$.

Verifying Whether the Set of Symmetric Matrices Is a Subspace

To determine if $\mathcal{S}$ is a subspace of M_{33} , we need to verify the three

properties outlined earlier.

1. Zero Matrix Inclusion

The zero matrix in M_{33} is:

$$\begin{aligned} & \backslash \\ 0 &= \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \\ & \backslash \end{aligned}$$

which is symmetric because $(0 = 0^T)$. Therefore, the zero matrix is in $(\mathcal{S})$.

2. Closure Under Addition

Suppose $(A, B \in \mathcal{S})$, i.e., both are symmetric matrices. Then:

$$\begin{aligned} & \backslash \\ A^T &= A, \quad B^T = B \\ & \backslash \end{aligned}$$

The sum:

$$\begin{aligned} & \backslash \\ C &= A + B \\ & \backslash \end{aligned}$$

has transpose:

$$\begin{aligned} & \backslash \\ C^T &= (A + B)^T = A^T + B^T = A + B = C \\ & \backslash \end{aligned}$$

Thus, (C) is symmetric, and the set $(\mathcal{S})$ is closed under addition.

3. Closure Under Scalar Multiplication

For $(A \in \mathcal{S})$ and scalar $(c \in \mathbb{R})$:

$$\begin{aligned} & \backslash \\ (cA)^T &= cA^T = cA \\ & \backslash \end{aligned}$$

which confirms that (cA) is symmetric. Therefore, $(\mathcal{S})$ is closed under

scalar multiplication.

Conclusion: Is the Set of Symmetric Matrices a Subspace?

Based on the above verification:

- The zero matrix is in $\mathcal{S}$.
- The sum of any two symmetric matrices is symmetric.
- The scalar multiple of a symmetric matrix is symmetric.

All three properties necessary for a subspace are satisfied. Consequently, the set of all symmetric 3×3 matrices is indeed a subspace of M_{33} .

Additional Insights and Applications

Dimension of the Subspace of Symmetric Matrices

Understanding the dimension helps grasp the size of the subspace within M_{33} .

- Number of free parameters in symmetric matrices:
- Diagonal entries: 3 (each can be any real number).
- Off-diagonal entries: Since $a_{ij} = a_{ji}$, only the entries above the diagonal are independent.
- Number of off-diagonal entries above the diagonal: 3 (positions $(1,2), (1,3), (2,3)$).

Total degrees of freedom:

$$3 \text{ (diagonal)} + 3 \text{ (above diagonal)} = 6$$

Thus, the subspace of symmetric matrices has dimension 6 within the 9-dimensional space $(M_{3 \times 3})$.

Practical Applications of Symmetric Matrices

Symmetric matrices are pervasive in various fields:

- Physics: Representing real quadratic forms and inertia tensors.
- Engineering: In structural analysis and vibrations.
- Statistics: Covariance matrices are symmetric and positive semi-definite.
- Computer Graphics: Transformations involving symmetric matrices for scaling and reflection.

Summary and Final Remarks

In summary, the set of all symmetric 3×3 matrices, $\mathcal{S}$, satisfies all the criteria to be a subspace of $M_{3 \times 3}$. It contains the zero matrix, is closed under addition, and is closed under scalar multiplication. These properties confirm that $\mathcal{S}$ is a subspace, specifically a 6-dimensional subspace within the 9-dimensional space of all 3×3 matrices.

Understanding the structure and properties of subspaces like symmetric matrices is crucial in linear algebra, facilitating advanced topics such as eigenvalue decomposition, quadratic forms, and matrix diagonalization. Recognizing such subspaces enables mathematicians and scientists to simplify complex problems by working within well-defined, manageable subsets of larger vector spaces.

In conclusion, the set of all symmetric matrices in $M_{3 \times 3}$ is a subspace of $M_{3 \times 3}$, providing a foundation for numerous theoretical and practical applications in mathematics and related disciplines.

Frequently Asked Questions

What are the key criteria to determine if a set of 3×3 matrices is a subspace of M_3 ?

The set must be closed under addition and scalar multiplication, contain the zero matrix, and satisfy the properties of vector addition and scalar multiplication inherent to M_3 .

How do we verify if the set of all symmetric 3×3 matrices forms a subspace of M_3 ?

We check if the set contains the zero matrix, is closed under addition, and is closed under scalar multiplication. Since symmetric matrices are closed under these operations, they form a subspace.

What is the significance of symmetry in determining whether a set of matrices is a subspace?

Symmetry ensures closure under addition and scalar multiplication, which are necessary for the set to be a subspace, provided the set contains the zero matrix.

Can the set of all symmetric 3×3 matrices be considered a vector space within M_3 ?

Yes, the set of all symmetric 3×3 matrices forms a vector space and thus is a subspace of M_3 because it satisfies all vector space axioms.

What role does the zero matrix play in confirming whether a set is a subspace?

The zero matrix must be included in the set; its presence is a fundamental requirement for the set to be a subspace.

Are all sets of 3×3 matrices that are symmetric necessarily subspaces?

Yes, all symmetric 3×3 matrices form a subspace because they satisfy the conditions of being closed under addition and scalar multiplication and include the zero matrix.

How can you test whether a given set of 3×3 matrices is a subspace if it is defined by certain properties?

You verify that the set contains the zero matrix, and that it is closed under addition and scalar multiplication, considering the defining properties of the set.

What is the dimension of the subspace of all symmetric 3×3 matrices?

The dimension is 6, since symmetric 3×3 matrices are determined by the three diagonal entries and the three entries above the diagonal.

Why do symmetric matrices form a subspace, and how does this relate to the set of all matrices M_3 ?

Because symmetric matrices are closed under addition and scalar multiplication and include the zero matrix, they form a subspace within M_3 , which contains all 3×3 matrices regardless of symmetry.

Additional Resources

Determine Whether Or Not The Indicated Set Of 3×3 Matrices Is A Subspace Of M_{33} . The Set Of All Symmetric Matrices

Introduction

Symmetry in matrices is a fundamental concept in linear algebra, with profound applications across mathematics, physics, computer science, and engineering. The question of whether a particular set of matrices forms a subspace of the larger space of all 3×3 matrices, denoted as M_{33} , is central to understanding the structure and properties of

these matrices. This article provides a comprehensive analysis of the set of all symmetric 3×3 matrices to determine if it constitutes a subspace of M_{33} , the space of all 3×3 matrices over a field (typically $\mathbb{R}$). We will explore the defining properties of subspaces, delve into the characteristics of symmetric matrices, and rigorously evaluate the criteria to reach an informed conclusion.

Understanding the Space M_{33} and Subspaces

What Is M_{33} ?

M_{33} represents the set of all 3×3 matrices with entries from a field, commonly the real numbers $\mathbb{R}$. Any matrix in M_{33} can be written as:

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

where each a_{ij} is a real number. The space M_{33} is a vector space over $\mathbb{R}$, with the usual matrix addition and scalar multiplication.

What Is a Subspace?

A subset W of a vector space V is called a subspace if it satisfies three key properties:

1. Contains the zero vector: The zero matrix (all entries zero) must be in W .
2. Closed under addition: If $A, B \in W$, then $A + B \in W$.
3. Closed under scalar multiplication: If $A \in W$ and $c \in \mathbb{R}$, then $cA \in W$.

These criteria ensure that W itself forms a vector space under the inherited operations from V .

The Set of All Symmetric Matrices in M_{33}

Definition of Symmetric Matrices

A matrix $(A \in M_{3 \times 3})$ is symmetric if it equals its transpose:

$$A = A^T$$

Explicitly, for a 3×3 matrix:

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{12} & a_{22} & a_{23} \\ a_{13} & a_{23} & a_{33} \end{bmatrix}$$

The pattern of symmetry implies that:

$$a_{ij} = a_{ji} \text{ for all } (i, j).$$

Thus, the set of all symmetric matrices in M_{33} consists of matrices with entries satisfying this symmetry condition.

Properties of Symmetric Matrices

Some key properties include:

- Closure under addition: The sum of two symmetric matrices is symmetric.
- Closure under scalar multiplication: Multiplying a symmetric matrix by a scalar results in a symmetric matrix.
- Contains the zero matrix: The zero matrix is symmetric since it equals its transpose.

These properties hint at the possibility that the set of symmetric matrices could form a subspace.

Evaluating Whether the Set of Symmetric

Matrices Is a Subspace

To establish whether the set of all symmetric 3×3 matrices is a subspace of M_{33} , we must verify the three subspace criteria.

1. Zero Vector Inclusion

The zero matrix:

$$\begin{aligned} & \backslash \\ O &= \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \\ & \backslash \end{aligned}$$

is symmetric because:

$$\begin{aligned} & \backslash \\ O^T &= O \\ & \backslash \end{aligned}$$

and thus, the zero matrix is in the set of symmetric matrices.

Conclusion: The first criterion is satisfied.

2. Closure Under Addition

Suppose (A, B) are symmetric matrices:

$$\begin{aligned} & \backslash \\ A &= \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{12} & a_{22} & a_{23} \\ a_{13} & a_{23} & a_{33} \end{bmatrix}, \\ & \quad \quad \quad \backslash \text{quad} \\ B &= \begin{bmatrix} b_{11} & b_{12} & b_{13} \\ b_{12} & b_{22} & b_{23} \\ b_{13} & b_{23} & b_{33} \end{bmatrix} \\ & \backslash \end{aligned}$$

Their sum:

$$\begin{aligned} A + B = & \begin{bmatrix} a_{11} + b_{11} & a_{12} + b_{12} & a_{13} + b_{13} \\ a_{12} + b_{12} & a_{22} + b_{22} & a_{23} + b_{23} \\ a_{13} + b_{13} & a_{23} + b_{23} & a_{33} + b_{33} \end{bmatrix} \end{aligned}$$

This sum is symmetric because:

- The off-diagonal entries satisfy:

$$(a_{12} + b_{12}) = (a_{21} + b_{21}) \quad \text{(since } A, B \text{ are symmetric)}$$

- The diagonal entries are arbitrary, but symmetry only depends on the off-diagonal entries being equal across the diagonal.

Result: The sum $(A + B)$ remains symmetric.

3. Closure Under Scalar Multiplication

For scalar $(c \in \mathbb{R})$ and symmetric matrix (A) :

$$\begin{aligned} cA = c & \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{12} & a_{22} & a_{23} \\ a_{13} & a_{23} & a_{33} \end{bmatrix} \\ = & \begin{bmatrix} c a_{11} & c a_{12} & c a_{13} \\ c a_{12} & c a_{22} & c a_{23} \\ c a_{13} & c a_{23} & c a_{33} \end{bmatrix} \end{aligned}$$

which remains symmetric, as the off-diagonal entries are scaled equally, preserving symmetry.

Conclusion: The set of all symmetric matrices satisfies all three criteria for being a subspace.

Additional Insights: Structure and Dimension of the Subspace

Understanding the structure of the set of symmetric matrices can deepen the appreciation of its role within M_{33} .

Parameterization of Symmetric Matrices

Any symmetric 3×3 matrix can be described by six independent parameters:

- Three diagonal entries: (a_{11}, a_{22}, a_{33}) .
- Three off-diagonal entries: $(a_{12} = a_{21}), (a_{13} = a_{31}), (a_{23} = a_{32})$.

Thus, the space of all symmetric matrices, denoted as (S_3) , is a vector space over $\mathbb{R}$ of dimension 6.

Basis for the Space of Symmetric Matrices

A basis can be constructed from matrices with specific entries:

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\[
\begin{aligned}
E_{11} &= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \\
E_{22} &= \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \\
E_{33} &= \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \\
E_{12} &= \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \\
E_{13} &= \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} \\
E_{23} &= \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}
\end{aligned}
\]
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Any symmetric matrix can be expressed as a linear combination of

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